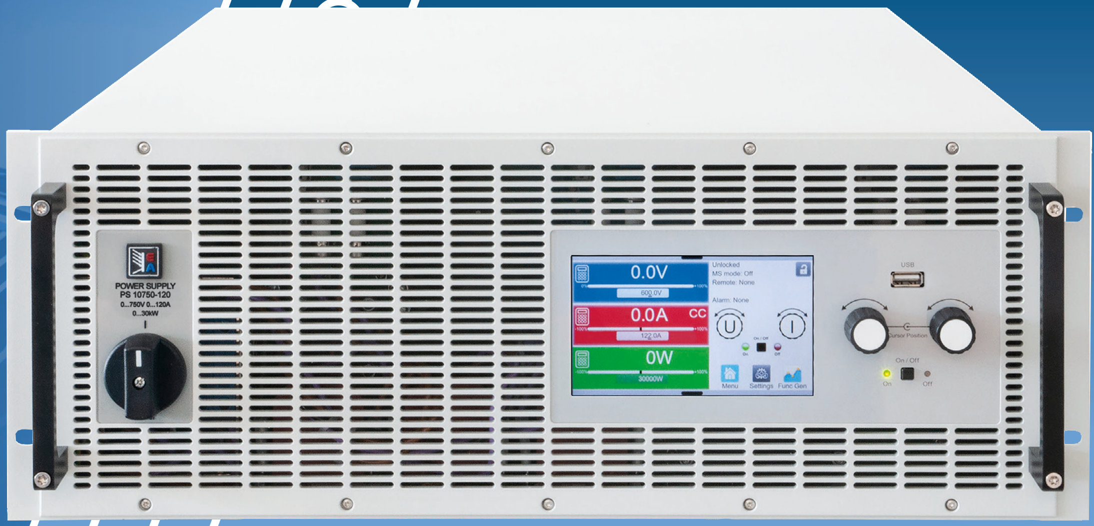
Elektro-Automatik



USER MANUAL

EA-PSB 10000 4U

Programmable bidirectional DC power supplies

Use, Remote Control, Function Generator

Revision: 01

TABLE OF CONTENTS

The part of this document that deals with the handling of features on the control panel is only valid for devices with firmwares “KE: 3.10”. “HMI: 4.09” and “DR: 1.0.2.20” or higher.

1. General

1.1 About this document

1.1.1 Preamble

Together with the separate installation manual, this document builds the documentation for use and control of the devices as listed in section *«1.1.3 Validity»*. It explains manual operation and other control related features.

1.1.2 Copyright

Modification and partial or complete usage of this document for other purposes as intended are forbidden and breach may lead to legal consequences.

1.1.3 Validity

This document is valid for the following equipment and its variants:

Model	Model	Model	Model
EA-PSB 10060-1000 4U	EA-PSB 10360-240 4U	EA-PSB 10920-125 4U	EA-PSB 12000-40 4U
EA-PSB 10080-1000 4U	EA-PSB 10500-180 4U	EA-PSB 11000-80 4U	
EA-PSB 10200-420 4U	EA-PSB 10750-120 4U	EA-PSB 11500-60 4U	

1.1.4 Symbols and warnings in this document

Warning and safety notices as well as general notices in this document are shown in a box with a symbol as follows. The symbols are also valid, where placed, also to mark specific spots on the device:

	Symbol for general safety notices (instructions and damage protection bans) or important information for operation
	Symbol for general notices

2. Operation and application (2)

2.1 Terms

The device is a combination of a power supply and an electronic load. It can work alternately in one of two superior operation modes which are distinguished from each other in several parts of this document below:

- **Source / source mode:**
    - the device works as a power supply, generating and providing DC voltage to an external DC load
    - in this mode, the DC terminal is considered as DC output
- **Sink / sink mode:**
    - the device works as an electronic load, sinking DC energy from an external DC source
    - in this mode, the DC terminal is considered as DC input

2.2 Operating modes

A device like this is internally controlled by different circuits, which shall bring voltage, current and power to the adjusted values and hold them constant, if possible. These circuits follow typical laws of control systems engineering, resulting in different operating modes. Every operating mode has its own characteristics which is explained below in short form.

2.2.1 Voltage control / Constant voltage

Voltage control is also called constant voltage operation (**CV**).

The voltage on the DC terminal of the device is held constant on the adjusted value, unless the current or the power according to $P = U_{DC} * I$ reaches the adjusted current or power limit. In both cases the device will automatically change to constant current or constant power operation, whatever occurs first. Then the voltage can't be held constant anymore and will sink (in source mode) or rise (in sink mode) to a value resulting from Ohm's law.

CV is available for both, sink and source mode, and primarily depends on the relation between voltage set value and voltage level on the DC terminal. The device will switch between both modes seamless when adjusting voltage. In source mode, the output voltage in CV mode is equal to its set value, while in sink mode the setting must always be lower than the input voltage in order to have the device draw current.

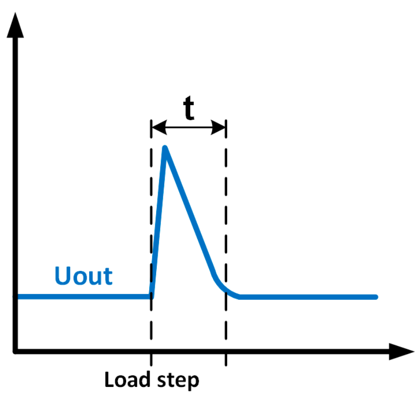
While the DC terminal is switched on and constant voltage mode is active, the condition "CV mode active" will be indicated on the graphics display by the abbreviation **CV** and this message will be passed as a signal to the analog interface, as well stored as status which can also be read via digital interface.

2.2.1.1 Voltage control peaks (source mode)

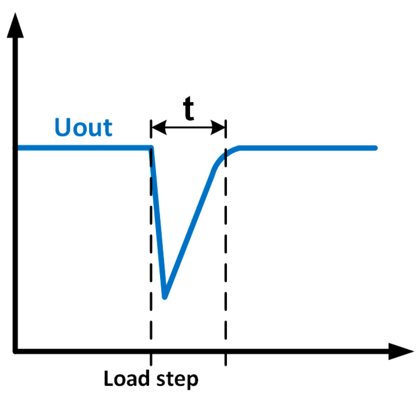
When working in constant voltage control (CV) and in source mode, the device's internal voltage regulator requires a small transient time to settle the voltage after a load step. Negative load steps, i.e. high load to lower load, will cause the output voltage to overshoot for a short time until compensated by the voltage regulator. The time it takes to settle the voltage can be influenced by switching the voltage control speed between the settings **Slow**, **Normal** and **Fast**, whereas Normal is the default. Setting **Slow** will result in a higher transient time and higher voltage drop, but less overshooting, where **Fast** is vice versa. Also see *«2.2.7 Dynamic characteristics and stability criteria»* and *«2.3.1.1 Sub menu "Settings"»*.

The same occurs with a positive load step, i.e. low load to high load. There the output collapses for a moment. The amplitude of the overshoot resp. collapse depends on the device model, the currently adjusted output voltage and the capacity on the DC terminal and can thus not be stated with a specific value.

Depictions:



Example for negative load step: the voltage on the DC terminal will rise above the adjusted value for a short time. t = transient time to settle the output voltage.



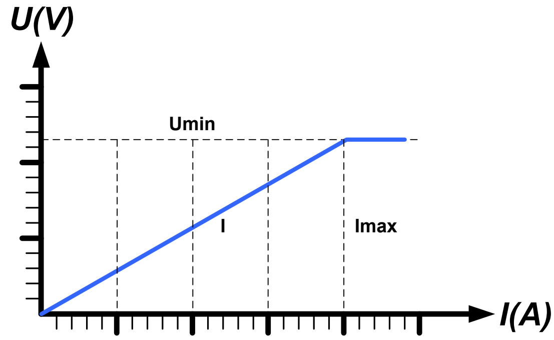
Example for positive load step: the voltage on the DC terminal will collapse below the adjusted value for a short time. t = transient time to settle the output voltage.

2.2.1.2 Minimum input voltage for maximum current (sink mode)

Due to technical reasons, all models in this series have a minimum internal resistance that requires a specific minimum input voltage (U_{MIN}) in order for the device to be able to sink its rated current (I_{MAX}). This minimum voltage is stated in the technical specifications in section *1.8.3* of the installation manual.

If less voltage than U_{MIN} is supplied, the load proportionally draws less current, which can be calculated easily.

See the principle view to the right.



2.2.2 Current control / constant current / current limiting

Current control is also known as current limiting or constant current mode (**CC**).

The current in the DC terminal of the device is held constant once the output current (source mode) to the load or the current consumed from the load (sink mode) reaches the adjusted limit. Then the device automatically switches to CC. In source mode, the current flowing from the power supply is only determined by the output voltage and the load's true resistance. Should the power consumption reach the adjusted power set value, the device will switch automatically to power limiting and set voltage and current according to P = U * I.

While the DC terminal is switched on and constant current mode is active, the condition "CC mode active" will be indicated on the graphics display by the abbreviation **CC** and this message will be passed as a signal to the analog interface, as well stored as status which can also be read as via digital interface.

2.2.2.1 Voltage overshootings

In certain situations it's possible that the device generates a voltage overshooting. Such situations are when the device is in CC, with the actual voltage being unregulated, and either a jump in the current set value is initiated which could bring the device out of CC or when the load is suddenly cut from the power supply by an external means. Peak and duration of the overshooting aren't exactly defined, but as rule of thumb it shouldn't exceed a peak of 1-2% of the rated voltage (on top of the voltage setting), while the duration mainly depends on the charging state of the capacities on the DC terminal and also the capacity value.

2.2.3 Power control / constant power / power limiting

Power control, also known as power limiting or constant power (**CP**), keeps the DC power constant if the current flowing to the load (source mode) or the current from the source (sink mode), in relation to the voltage, reaches the adjusted limit according to P = U * I (sink mode) or $P = U^2 / R_{LOAD}$ (source mode).

In source mode, the power limiter then regulates the output current according to $I = sqr(P / R_{LOAD})$.

Power limiting operates according to the auto-range principle such that at lower voltages higher current can flow and vice versa, always in order to maintain constant power within the range P_N (see the diagram to the right).

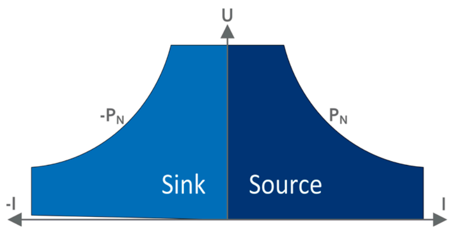


Figure 1 - Power range

While the DC terminal is switched on and constant power mode is active, the condition "CP mode active" will be indicated on the graphics display by the abbreviation **CP**, as well stored as status which can also be read via digital interface.

2.2.3.1 Power derating (only standard 30 kW models)

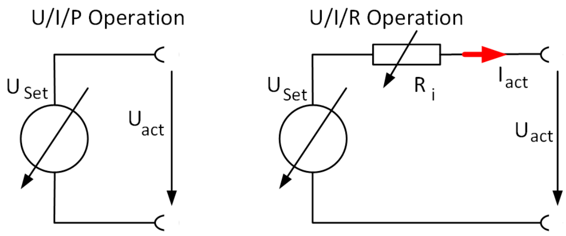
All models in this series can also operate on a three-phase supply with 208 V (USA, Japan). In order to limit the AC current when running on the low input voltage, the devices would automatically switch into a derating mode that reduces the available DC power to a maximum of 18 kW. The switchover is determined once when the device is powered and it depends on the AC supply voltage being present in that moment. Should the voltage go up again later, the device would remain in derating mode as long as it's powered, because the switchover into and out of derating mode isn't dynamic. The full rated power is thus only available with AC voltages from 380 V.

Once derated, the device would show a permanent information in the display and all values related to the power are reduced in their adjustment range. This also applies to master-slave operation of derated units.

2.2.4 Internal resistance control (source mode)

Internal resistance control (abbr. CR) of power supplies is the simulation of a virtual internal resistor which is in series to the load. According to Ohm's law, this resistance causes a voltage drop, which will result in a difference between adjusted output voltage and actual output voltage. This will work in constant current mode as well as in constant power mode, but here the output voltage will differ even more from the adjusted voltage, because then constant voltage is not active.

The available resistance range of a particular model is given in the technical specifications. The voltage control, in dependency of the resistance set value and the output current, is done by calculation in a microcontroller, being only a little slower than other controllers inside the main control circuit. Clarification:



$$U_{Act} = U_{Set} - I_{Act} * R_{Set} \Big|_{P_{Set}, I_{Set}}$$

$$P_{Ri} = (U_{Set} - U_{Act}) * I_{Act}$$

!	*With resistance mode being activated the function generator will be unavailable and the actual power value provided by the device does not include the simulated power dissipation of Ri.*

2.2.5 Resistance control / constant resistance (sink mode)

In sink mode, that is when the device is working as electronic load, the operating principle is based on a variable internal resistance. Constant resistance mode (CR) is almost a natural characteristic. The load attempts to set the internal resistance to the user defined value by determining the input current depending on the input voltage according to formula $I_{IN} = U_{IN} / R_{SET}$, which is derived from Ohm's law.

With series PSB 10000, the difference between an external voltage supplied to the device and the set value of voltage determines the true current. There are two situations:

a) The voltage on the DC terminal is higher than the voltage set value

In this situation, the above formula extends to $\mathbf{I_{IN} = (U_{IN} - U_{SET}) / R_{SET}}$.

An example: the supplied voltage on the DC terminal is 200 V, the resistance R_{SET} is adjusted to 10 Ω and the voltage set value U_{SET} is set to 0 V. When switching the DC terminal on the current should go to 20 A and the actual resistance R_{ACT} should show approx. as 10 Ω. When adjusting the voltage set value U_{SET} to 100 V now, the current would decrease to 10 A while the actual resistance R_{MON} should remain at 10 Ω.

b) The voltage on the DC terminal is equal to or lower than the voltage set value

The PSB 10000 would not draw any current and enter CV mode. In a situation where the supplied input voltage is approx. equal to or oscillating around the voltage set value, the sink mode would permanently toggle between CV and CR. It's hence not advisable to adjust the voltage set value to the same level as the external source.

The internal resistance is naturally limited between almost zero and maximum, where the resolution of current control becomes very inaccurate. Because the internal resistance can't have a value of zero, the lower limit is defined to an achievable minimum. This ensures that the internal electronic load, at very low input voltages, can consume a high input current from the source, up to the adjusted current set value.

While the DC terminal is switched on and constant resistance mode is active, the condition "CR mode active" will be indicated on the graphics display by the abbreviation **CR**, as well it will be stored as internal status which can be read via digital interface.

2.2.6 Sink-source mode switching

The switchover between sink and source mode happens automatically and only depends on the device's voltage setting and actual value on the DC terminal or the remote sense connector, if in use.

It means, that when connecting an external voltage source to the DC terminal, only the voltage set value determines the operation mode. When connecting an external load which can't generate a voltage, only source mode can be run.

Rules for applications with an external voltage source connected:

- If the voltage set value is higher than the actual voltage of the external source, the device will run in source mode
- If the voltage set value is lower, it will run in sink mode

To run one of both modes explicitly, i.e. without automatic switchover, the following is required:

- For "source only mode" adjust the current set value for the sink mode to 0
- For "sink only mode" adjust the voltage set value to 0

2.2.7 Dynamic characteristics and stability criteria

When working in sink mode, the device becomes an electronic load, characterized by short rise and fall times of the current, which are achieved by a high bandwidth of the internal control circuit.

In case of testing sources with own control circuits, like for example power supplies, a control instability may occur. This instability is caused if the complete system (feeding source and electronic load) has too little phase and gain margin at certain frequencies. 180 ° phase shift at > 0dB amplification fulfills the condition for an oscillation and results in instability. The same can occur when using sources without own control circuit like batteries and when the connection cables are highly inductive or inductive-capacitive.

The instability isn't caused by a malfunction of the device, but by the behavior of the complete system. An improvement of the phase and gain margin can solve this. In practice, this is primarily done by switching the internal voltage regulator between dynamics modes called **Slow**, **Fast** and **Normal**. The switch is either found in the device settings (see section *2.3.1.1*) or the quick menu (see section *2.3.5*). The user can only try the different settings to see if the desired effect is achieved. Should there be an improvement due to one of these settings, but the oscillation remains, an additional measure can be to install a capacitor directly at the DC terminal, perhaps alternatively to the remote sense input, if connected to the source. The capacitor's value to achieve the expected result is not defined and has to be found out. We recommend:

- 10/60/80 V models: 1000uF....4700uF
- 200/360 V models: 100uF...470uF
- 500 V models: 47uF...150uF
- 750/920/1000 V models: 22uF...100uF
- 1500/2000 V models: 4.7uF...22uF

2.2.8 Actual value filter

From a certain set of firmwares, particularly HMI 4.05 and KE 3.08, the device supports a user-configurable filtering feature. Its purpose is to periodically smoothen the actual values as they are shown on the screen or put out as digital or analog values. The filtering, if activated, is working in a way that it read an adjustable number of samples, i. e. measured actual values of voltage, current and power into an internal buffer, then calculates an average and exports the result as the next new set of actual values.

The user can select between modes **Fixed** and **Moving**, which differ as follows:

- **Fixed**: the selected number of samples is used to calculate the average, then the internal temporary sample buffer is purged and x new values are sampled
- **Moving**: the average is always calculated over the last x samples while the internal buffer isn't purged, but every new sample pushes all previous ones up so the values in the buffer move. This also means, that several subsequent average calculations are done with partially the same samples

Additionally to the mode, the user can select the size of the internal buffer (also called filtering stage) between 2 and 24. Together with the general fact that the device can deliver a new set of actual values every 20 ms, at least when the filtering is turned off, the filter delays every next new set pf values by this factor. It means, with the highest setting of 24 new actual values are only put out on the interfaces and screen approximately every 480 ms.

2.2.9 Fast discharge

All models in this series are bidirectional and due to their built-in sink capability they can discharge their own output capacities and also those of a possibly connected, external source by sinking a high current, up the rated one. This way of ramping the output voltage down quickly is only designed to work while the DC terminal remains switched on.

After switching it off, the main power stage would stop sinking energy, but a smaller, internal electronic load would take over and ensure to discharge the voltage in under 10 seconds to below 60 V, as part of a safety requirement. After reaching the threshold of 60 V, the voltage would continue to sink towards 0 V, but slower.

The feature **Fast discharge**, as available from firmwares KE 3.10 and HMI 4.09 for all 10000 series power supplies, is a new functionality aiming to discharge the output voltage even quicker. It can be activated if needed (see section *2.3.1.1*). Three adjustable parameters belong to it, the **Fast discharge voltage**, the **Fast discharge current** and the F**ast discharge duration**. The voltage value will determine to down what level of voltage the fast discharge action is performed, together with the current, which has a primary impact. The device would, in the moment of the action, overwrite the currently adjusted set value of sink current by the fast discharge current and the one of the sink power to 102% P_{Rated}.

The actual duration of the discharge action also depends on the maximum current a particular device model can sink, as well as the model specific output capacity, and therefore isn't defined. The parameter of **Fast discharge time** allows to extend the duration wide enough for the feature to work correctly, as well as narrow it down to the necessary minimum. The maximum of 5 seconds is supposed to be enough to always discharge the output voltage even to 0 V, except a connected external source would prevent that.

As a side effect of the activated feature, the DC terminal status would remain as "on" as long as the discharge action runs after the user commanded to switch the DC terminal off manually by button On/Off or per remote control command, no matter what stop condition occurs first, the reached voltage threshold or the elapsed duration. It's expected that the output voltage would jump down to the adjusted threshold (**Fast discharge voltage**) in a split second, given the **Fast discharge current** is high enough, and, in case the threshold isn't set to 0 V, continue to sink, but as slow as when **Fast discharge** is deactivated.

Clarification:

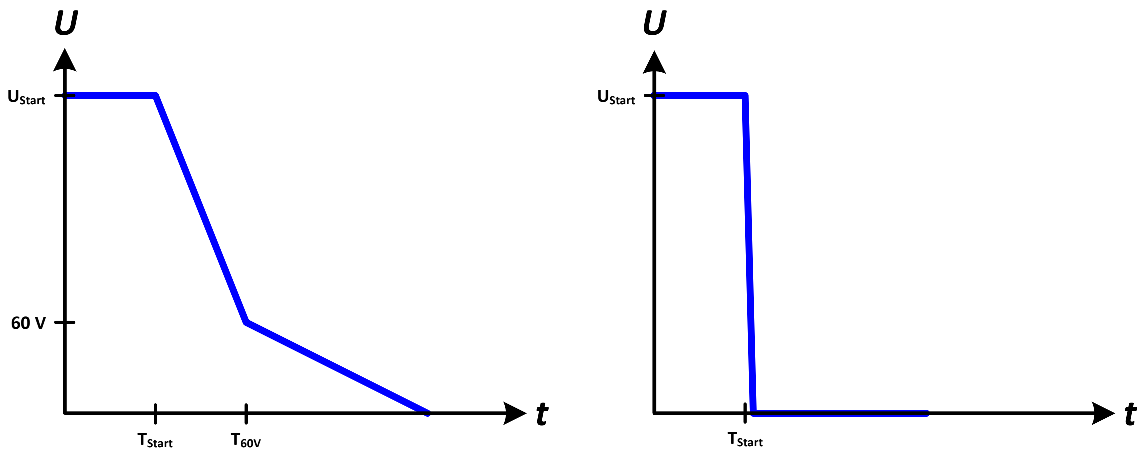


Figure 2 - Comparison of the voltage run after switching DC off without (left diagram) and with Fast discharge (to 0 V, right diagram) being activated

> *Since this a software feature, it won't work if the DC terminal is switched by other reasons, such as all alarms which would also switch DC off. That includes the moment when switching the device off.*

2.2.10 STBY zero stabilization

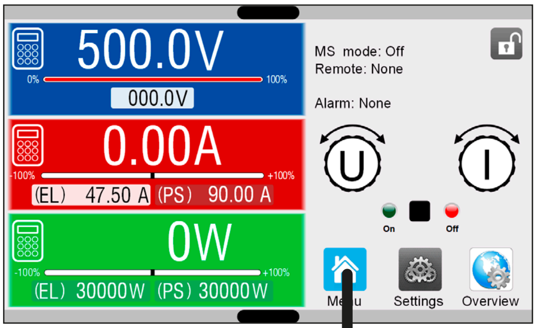
This feature, as available from firmwares KE 3.10 and HMI 4.09 for all models of the 10000 series, is deactivated by default and be activated in the settings menu (see section *2.3.1.1*), if needed. The goal is to stabilize the actual voltage value after the DC terminal has been switched off and after the voltage has sunken below a certain threshold (here: 3 V, model independent). The **STBY** in the name stand for stand-by and refers to the status of the DC terminal when switched off.

Due to technical reasons, the display actual voltage and the true voltage on the DC terminal can fluctuate and also remain slightly over 0 V. Those reasons are the switching power supply design, parasitic capacities and measurement errors. This feature, when activated, would set the actual voltage values to 0 V as long as the measured value on the DC terminal is below the threshold of 3 V. Since the device continuously measure the voltage on its DC terminal, also when DC is switched off, it would measure the voltage of a connected, external source as well. In both situations, voltage leaps between 3 V and 0 V in both directions are expected and normal. This suppresses the small voltage fluctuations around the zero point.

2.3 Manual operation (2)

⚠	While manually operated and while also being connected to any remote control equipment via any of the interfaces, the device could be taken over into remote control anytime without warning or request for confirmation. It's thus recommended to block remote control by activating the 'Local' mode for the duration of manual operation.

2.3.1 Configuration via the menu

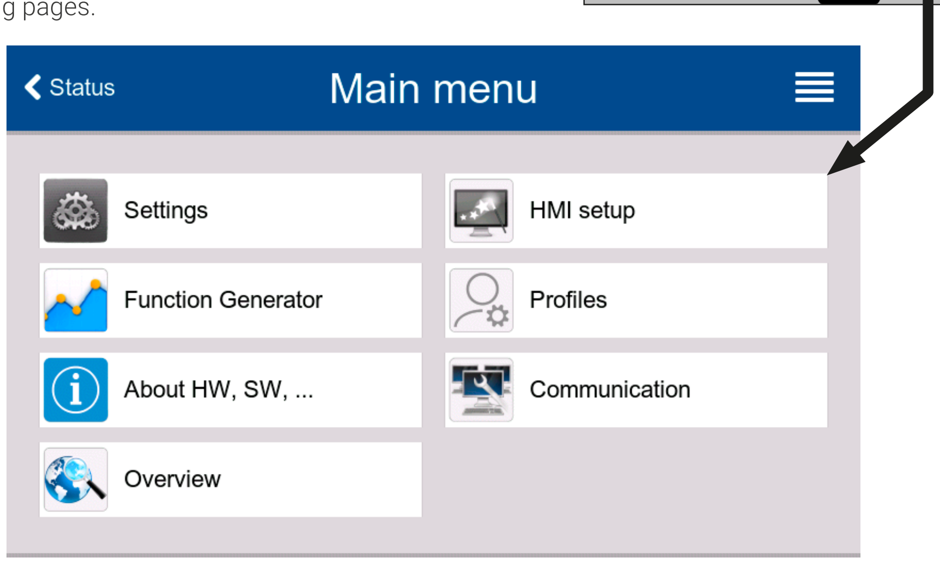


The settings menu is meant for the configuration of all operating parameters which are not constantly required. The menu is accessed by finger touch on the **Menu** touch area, but only while the DC terminal is switched off. See the figure to the right.

While the DC terminal is switched on the settings menu will not be shown, but some status information.

Menu navigation is also done by finger touch. Inside menus, all values are adjusted using the numeric pad that pops up when tapping a value.

Many settings are self-explanatory, others are not. Those will be explained on the following pages.



2.3.1.1 Sub menu “Settings”

This sub menu can be accessed directly from the main screen by tapping the Settings button.

<table>
<tr><th>Group</th><th>Parameters & description</th></tr>
<tr><td rowspan="2">Presets</td><td>U, I, P, R</td></tr>
<tr><td>Presetting of all set values via on-screen numeric pad.</td></tr>
<tr><td rowspan="2">Protection</td><td>OVP, OCP, OPP</td></tr>
<tr><td>Adjust the thresholds of the protections</td></tr>
<tr><td rowspan="2">Limits</td><td>U-max, U-min etc.</td></tr>
<tr><td>Define the adjustment limits (find more information in «2.3.2 Adjustment limits»)</td></tr>
<tr><td rowspan="2">User events</td><td>UVD, OVD etc.</td></tr>
<tr><td>Define supervision thresholds which can trigger user defined events (find more information in «3.5.2.1. User defined events» in the installation manual)</td></tr>
<tr><td rowspan="16">General</td><td>Allow remote control</td></tr>
<tr><td>If remote control isn’t allowed, the device can’t be controlled remotely over either the digital or analog interfaces. This situation will be shown as Local in the status area on the main display. Also see section 1.9.6.1 in the installation manual.</td></tr>
<tr><td>Analog interface priority</td></tr>
<tr><td>Activates or deactivates the priority of the analog interface regarding the action of taking over remote control by pin REMOTE. Find details in «2.4.4.8 Analog interface priority».</td></tr>
<tr><td>R mode</td></tr>
<tr><td>Activates or deactivates the internal resistance control. If activated, the set values and actual of resistance will be shown on the main screen. For details refer to «2.2.4 Internal resistance control (source mode)» in this document and «3.4.3 Manual adjustment of set values» in the installation manual.</td></tr>
<tr><td>Voltage controller speed</td></tr>
<tr><td>(Switching the speed only works if the device has already been <u>delivered</u> with firmware KE 3.02 and DR 1.0.2.20 or higher)
This switch can be used to select the internal voltage controller speed which, as a result, impacts the voltage settling time. For more information refer to «2.2.7 Dynamic characteristics and stability criteria».
• Slow = the voltage controller will be a little slower, the oscillation tendency will decrease
• Normal = the voltage controller is on standard speed (Default)
• Fast = the voltage controller will be a little faster, the oscillation tendency will increase</td></tr>
<tr><td>SEMI F47</td></tr>
<tr><td>(Only displayed if the device has already been <u>delivered</u> with firmware KE 3.02 or higher)
Activates or deactivates a feature called SEMI F47 which is related to the equally named standard. See «4.2 SEMI F47» for more information.</td></tr>
<tr><td>Actual value filter mode</td></tr>
<tr><td>By selection of Fixed or Moving it activates a filter function for the actual values (voltage, current, power), as measured on the DC terminal of the device and shown on the HMI screen, as well as signaled on the analog and digital interfaces. For details refer to «2.2.8 Actual value filter».</td></tr>
<tr><td>Actual value filter buffer size</td></tr>
<tr><td>Belongs to Actual value filter mode, see above and «2.2.8 Actual value filter». Adjustable range: 2...24</td></tr>
<tr><td>STBY zero stabilization</td></tr>
<tr><td>Activates or deactivates the feature, as described in «2.2.10 STBY zero stabilization».</td></tr>
</table>

Group	Parameters & description
General	**Fast discharge**
	Activates or deactivates the feature, as described in *«2.2.9 Fast discharge»*.
	Fast discharge voltage
	Belongs to **Fast discharge**. Defines the threshold in Volts, to which the feature shall discharge the DC output voltage to. Range: **0V**...102% U_{Nom}
	Fast discharge current
	Belongs to **Fast discharge**. Defines the maximum sink current in Amperes that is used to discharge the capacities on the DC terminal, in order to ramp the voltage down quicker. Range: **0A**...102% I_{Nom}
	Fast discharge duration
	Belongs to **Fast discharge**. Defines the maximum duration in milliseconds for the feature being active. Range: **0ms...5000ms**
Analog interface	**Range**
	Selects the voltage range for the analog set values, actual values and reference voltage output. • **0...5V** = Range is 0...100% for set /actual values, reference voltage will be 5 V • **0...10V** = Range is 0...100% for set /actual values, reference voltage will be 10 V Also see *«2.4.4 Remote control via the analog interface»*
	REM-SB Level
	Selects how the input pin REM-SB of the analog interface shall be working regarding levels (see *«2.4.4.3 Analog interface specification»*) and logic: • **Normal** = Levels and function as described in the table in section *2.4.4.3* • **Inverted** = Levels and function will be inverted Also see *«2.4.4.7 Application examples»*
	REM-SB Action
	Selects how the input pin REM-SB of the analog interface shall operate regarding the DC terminal condition outside of analog remote control: • **DC Off** = The pin can only switch the DC terminal off • **DC On/Off** = The pin can switch the DC terminal off and on again, if it has been switched on before from a different control location
	Pin 6
	Pin 6 of the analog interface (see *«2.4.4.3 Analog interface specification»*) is by default assigned to signal both device alarms OT and PF. This parameter allows to also enable signaling only one of both (3 possible combinations): • **Alarm OT** = Pin 6 signals only alarm OT • **Alarm PF** = Pin 6 signals only alarm PF • **Alarm PF + OT** = Default, pin 6 signals either PF or OT
	Pin 14
	Pin 14 of the analog interface (see section *2.4.4.3*) is by default assigned to only signal the device alarm OVP. This parameter allows to also enable signaling the device alarms OCP and OPP in 7 possible combinations: • **Alarm OVP** = Pin 14 signals only OVP • **Alarm OCP** = Pin 14 signals only OCP • **Alarm OPP** = Pin 14 signals only OPP • **Alarm OVP+OCP** = Pin 14 signals OVP or OCP • **Alarm OVP+OPP** = Pin 14 signals OVP or OPP • **Alarm OCP+OPP** = Pin 14 signals OCP or OPP • **Alarm OVP+OCP+OPP** = Pin 14 signals any of the three alarms

Group	Parameters & description
Analog interface	**Pin 15**
	Pin 15 of the analog interface (see section *2.4.4.3*) is by default assigned to only signal the control mode CV. This parameter allows to enable signaling the DC terminal status (2 options): • **Regulation mode** = Pin 15 signals the CV control mode • **DC status** = Pin 15 signals the DC terminal status
	VMON/CMON
	Configures how the actual values of voltage and current are represented. If not listed otherwise, the setting doesn't affect the selected signal range (0-5 V or 0-10 V). • **Default** = Current (sink or source mode) on pin 10 (CMON), voltage on pin 9 (VMON) • **Actual current (EL)** = Pin 10 only signals the actual current in sink mode (EL) • **Actual current (PS)** = Pin 10 only signals the actual current in source mode (PS) • **Mode A** = Current of source mode (PS) on pin 9, current of sink mode (EL) on pin 10, the voltage is not signaled in this mode • **Mode B** = Current of sink mode (EL) on pin 9, current of source mode (PS) on pin 10, the voltage is not signaled in this mode • **Actual current (EL) + (PS)** = Pin 10 signals a combination of the current in sink and source mode as -100%...0...100% whereas 0% is put in the center of the analog signal range, it means either at 5 V or 2.5 V. Each of both actual values only has half resolution.
DC terminal	**State after power ON**
	Determines the condition of the DC terminal after power-up. • **Off** = The DC terminal is always off after switching on the device • **Restore** = The DC terminal state will be restored from the last switch-off The factory default of this setting, also after a device reset, is "Off". Setting this to "Restore" solely lies within the responsibility of the operator, as the device could automatically start to supply voltage after boot-up, depending on the restored state of the DC terminal. Be careful!
	State after PF alarm
	Determines the condition of the DC terminal after a power fail (PF) alarm: • **Off** = The DC terminal remains off • **Auto** = The DC terminal will switch on again after the PF alarm cause is gone, if it has been switched on before the alarm occurred
	State after remote
	Determines the condition of the DC terminal after leaving remote control either manually or by command: • **Off** = The DC terminal will always be off after leaving remote control • **Auto** = The DC terminal will keep the last state
	State after OT alarm
	Determines the condition of the DC terminal after an overtemperature (OT) alarm, once the device has cooled down: • **Off** = The DC terminal will remain off • **Auto** = The device will automatically restore the situation before the OT alarm, which usually means the DC terminal to be on
Master-slave	**Mode**
	Selecting **Master** or **Slave** enables the master-slave mode (MS) and defines the position for the unit in the MS system. For details see *«4.1 Parallel operation in master-slave (MS)»*.

Group	Parameters & description
Master-slave	**Termination resistor**
	Activates or deactivates the so-called bus termination of the digital master-slave bus via a switchable resistor. Termination must be activated on both bus ends, unless the device on any end is the master.
	Bias resistors
	Additionally to the regular termination resistor (TERM) this activates two bias resistor, if required, to help stabilize the bus further. Tap on the information symbol for a graphical depiction.
	Backlight off after 60s
	If activated, it will switch off the display's backlight after 60 seconds of inactivity. This settings is primarily intended for slave units where the display isn't supposed to be permanently on. It's identical to the setting in menu **HMI setup**.
	Initialize system
	Tapping this touch area will repeat the initialization of the master-slave system in case the detection of all slave units by the master was unsuccessful, so the system would have less total power than expected, or has to be repeated manually in case the master unit couldn't detect a missing slave or one slave has failed.
USB logging	**Log file separator format**
	Defines the format of CSV files generated from logging files (also see section *2.3.4* in this document, and section *1.9.6.5* in the installation manual). This setting also affects other features where a CSV file can be loaded or saved. • **US** = Comma as column separator (US standard for CSV files) • **Default** = Semicolon as column separator (german/european standard for CSV files)
	Logging with units (V,A,W)
	CSV files generated from USB logging by default add physical units to values. This can be deactivated here.
	USB logging
	Activates/deactivates logging to USB stick. For more information refer to *«2.3.4 Recording to USB stick (logging)»*.
	Logging interval
	Defines the time between two records in the log file. Selection: **500ms**, **1s**, **2s**, **5s**
	Start/stop
	Defines how the USB logging is started and stopped. • **Manual** = Logging only starts and stops upon user interaction on the HMI, by accessing touch button in the quick menu. • **At DC on/off** = Logging starts and stops with every change of state on the DC terminal, no matter if caused by the user, software or a device alarm. Attention: Every next start will create a new log file.
Reset / Restart	**Reset device to defaults**
	This touch area will initiate a reset of most settings (HMI, profile etc.) to factory default.
	Restart
	Triggers a warm start

2.3.1.2 Sub menu "Profiles"

See *«2.3.6 Loading and saving user profiles»*.

2.3.1.3 Sub menu "Overview"

This menu page displays an overview of the set values (U, I, P or U, I, P, R), device alarm thresholds, event settings, adjustment limits, as well as an alarm history which lists the number of device alarms that occurred since the device has been powered.

2.3.1.4 Sub menu "About HW, SW, ..."

This menu page displays an overview of device relevant data such as serial number, article number etc.

2.3.1.5 Sub menu "Function Generator"

See *«3. The function generator»*.

2.3.1.6 Sub menu "Communication"

This sub menu offers settings for digital communication via the built-in interfaces USB and Ethernet and also for the optional interface modules of IF-AB series.

There are furthermore adjustable communication timeouts. For more information about these timeout refer to the external, on USB stick included documentation "Programming guide ModBus & SCPI". The USB itself doesn't require any settings.

Settings for the internal Ethernet port

IF	Settings	Description
Ethernet (internal)	**DHCP**	The IF allows a DHCP server to allocate an IP address, a subnet mask and a gateway. If no DHCP server is in the network then network parameters will be set as defined below.
	IP address	Manually allocate an IP address
	Subnet mask	Manually allocate a subnet mask
	Gateway	Manually allocate a gateway address, if required
	DNS address	Manually allocate addresses of a Domain Name Server (DNS), if required
	Port	Select port in the range 0...65535. Default: **5025** Reserved ports: 502, 537
	Host name	User definable host name
	Domain	User definable domain
	MAC address	of the internal Ethernet port

Settings for the optional interface modules (IF-AB-xxx)

IF	Settings	Description
Profibus	**Node Address**	Selection of the Profibus or node address of the device within range 1...125 via direct input
	Function Tag	String input box for a user-definable text which describes the Profibus slave function tag. Max. length: 32 characters
	Location Tag	String input box for a user-definable text which describes the Profibus slave location tag. Max. length: 22 characters
	Installation Date	String input box for a user-definable text which describes the Profibus slave installation date tag. Max. length: 40 characters
	Description	String input box for a user-definable text which describes the Profibus slave. Max. length: 54 characters
	Manufacturer ID	Registered manufacturer ID with the Profibus organization
	Ident number	Product identification number, same as in the GSD file

IF	Settings	Description
RS232	**Baud rate**	The baud rate is selectable, other serial settings can't be changed and are defined like this: 8 data bits, 1 stop bit, parity = none Baud rates: **2400Bd**, **4800Bd**, **9600Bd**, **19200Bd**, **38400Bd**, **57600Bd**, **115200Bd**

IF	Settings	Description
Profinet/IO (1 & 2 Port)	**Host name**	Free choice of host name (default: **Client**)
	Domain name	Free choice of Domain (default: **Workgroup**)
	Function Tag	String input box for a user-definable text which describes the Profinet slave function tag. Max. length: 32 characters
	Location Tag	String input box for a user-definable text which describes the Profinet slave location tag. Max. length: 22 characters
	Installation Date	String input box for a user-definable text which describes the Profibus slave installation date tag. Max. length: 40 characters
	Description	String input box for a user-definable text which describes the Profibus slave. Max. length: 54 characters
	Station Name	String input box for a user-definable text which describes the Profinet station name. Max. length: 200 characters

IF	Settings	Description
Slot Ethernet / ModBus-TCP (1 & 2 Port)	**DHCP**	The IF allows a DHCP server to allocate an IP address, a subnet mask and a gateway. If no DHCP server is in the network then network parameters will be set as defined below.
	IP address	This option is activated by default. An IP address can be manually allocated.
	Subnet mask	Here a subnet mask can be defined if the default subnet mask is not suitable.
	Gateway	Here a gateway address can be allocated if required..
	DNS address	Here the addresses of the first and second Domain Name Servers (DNS) can be defined, if needed.
	Port	Range: 0...65535, default port: **5025** = Modbus RTU Reserved ports: 502, 537
	Host name	User definable host name (default: **Client**)
	Domain	User definable domain (default: **Workgroup**)
	MAC address	of the internal Ethernet port
	Speed / Duplex Port 1	Manual selection of transmission speed (**10MBit**/**100MBit**) and duplex mode (**full**/**half**). It's recommended to use the **Auto** option and only revert to another option if Auto fails.
	Speed / Duplex Port 2	Different Ethernet port settings for 2-port modules are possible, as these include an Ethernet switch

IF	Settings	Description
CANopen	**Baud Rate**	CAN bus baud rate selection that is used by the CANopen interface. **Auto** = Automatic detection **LSS** = Baud rate and node address are assigned by the bus master Fixed baud rates: **10kbps**, **20kbps**, **50kbps**, **100kbps**, **125kbps**, **250kbps**, **500kbps**, **800 bps**, **1Mbps**
	Node Address	Selection of the CANopen node address in the range **1**...**127**

IF	Settings	Description
CAN	**Baud rate**	Setup of the CAN bus speed or baud rate in typical value between 10 kbps and 1Mbps. Default: **500kbps**
	ID Format	Selection of the CAN ID format and range between **Standard** (11 Bit ID, 0h...7ffh) and **Extended** (29 Bit, 0h...1fffffffh)
	Termination	Activates or deactivates CAN bus termination with a built-in resistor. Default: off
	Data length	Determines the DLC (data length) of all messages sent from the device. **Auto** = length can vary between 3 and 8 bytes **Always 8 Bytes** = length is always 8, filled up with zeros
	Base ID	Setup of the CAN base ID (11 Bit or 29 Bit, hex format). Default: **0h**
	Broadcast ID	Setup of the CAN broadcast ID (11 Bit or 29 Bit, hex format). Default: **7ffh**
	Base ID Cyclic Read	Setup of the CAN base ID (11 Bit or 29 Bit, hex format) for cyclic read of several object groups. The device will automatically send object data to the IDs defined with this setting. For more information refer to the programming guide. Default: **100h**
	Base ID Cyclic Send	Setup of the CAN base ID (11 Bit or 29 Bit, hex format) for cyclic send of set values along with status. For more information refer to the programming guide. Default: **200h**
	Cyclic Read Time: Status	Activation/deactivation and time setting for the cyclic read of status from the adjusted **Base ID Cyclic Read** Range: 20 ms...5000 ms. Default: **0ms** (deactivated)
	Cyclic Read Time: Set values (PS)	Activation/deactivation and time setting for the cyclic read of set values of U & I (source mode) from the adjusted **Base ID Cyclic Read + 2**. Range: 20 ms...5000 ms. Default: **0ms** (deactivated)
	Cyclic Read Time: Limits values 1 (PS)	Activation/deactivation and time setting for the cyclic read of adjustment limits of U & I (source mode) from the adjusted **Base ID Cyclic Read + 3**. Range: 20 ms...5000 ms. Default: **0ms** (deactivated)
	Cyclic Read Time: Limits values 2 (PS)	Activation/deactivation and time setting for the cyclic read of adjustment limits of P & R (source mode) to the adjusted **Base ID Cyclic Read + 4**. Range: 20 ms...5000 ms. Default: **0 ms** (deactivated)
	Cyclic Read Time: Actual	Activation/deactivation and time setting for the cyclic read of actual values from the adjusted **Base ID Cyclic Read + 1.** Range: 20 ms...5000 ms. Default: **0ms** (deactivated)
	Cyclic Read Time: Set values (EL)	Activation/deactivation and time setting for the cyclic read of set values of I, P and R (sink mode) from the adjusted **Base ID Cyclic Read + 5**. Range: 20 ms...5000 ms. Default: **0ms** (deactivated)
	Cyclic Read Time: Limit values (EL)	Activation/deactivation and time setting for the cyclic read of adjustment limits of I, P and R (sink mode) from the adjusted **Base ID Cyclic Read + 6**. Range: 20 ms...5000 ms. Default: **0ms** (deactivated)
	Module firmware	CAN module firmware version

Further communication related parameters

Group	Parameters & description
Timeouts	**TCP keep-alive (slot) / TCP keep-alive (internal)**
	Activates/deactivates the keep-alive network functionality for the internal Ethernet port and for an a standard Ethernet module (IF-AB-ETHxx), if installed in the slot. The keep-alive network packets are used to keep the socket connection open. As long as keep-alive is present in the network, the device will disable the Ethernet timeout. Also see below at **Timeout ETH**.
	Timeout USB/RS232
	Defines the max. time between two subsequent bytes or blocks of a transferred message. For more information about the timeout refer to the external programming documentation "Programming ModBus & SCPI". Default value: **5ms**, Range: 5 ms...65535 ms
	Timeout ETH (internal) / Timeout ETH (slot)
	Defines a timeout after which the device would close the socket connection if there was no command communication between the controlling unit (PC, PLC etc.) and the device for the adjusted time. The timeout is ineffective as long as option **TCP keep-alive** is enabled for the particular interface and the keep-alive network service is running. A setting of 0 would deactivate the timeout permanently. Default value: **5s**, Range: 0 / 5 s...65535 s (0 = timeout deactivated)
	Interface monitoring / Timeout Interface monitoring
	Activates/deactivates the interface monitoring (see *«2.4.3.3 Interface monitoring»*). Default values: off, **5s** / Range: 1 s...65535 s
Protocols	**Communication protocols**
	Enables or disables SCPI or ModBus communication protocols for the device. The change is immediately effective. Only one of both can be disabled.
	ModBus specification compliance
	Allows to switch from **Limited** (default setting) to **Full** which makes the device send messages in ModBus RTU or ModBus TCP format which fully comply to the specification and are compatible to softwares available on the market. With **Limited** the device would still use the old, partially wrong message format (see the separate programming guide for details).

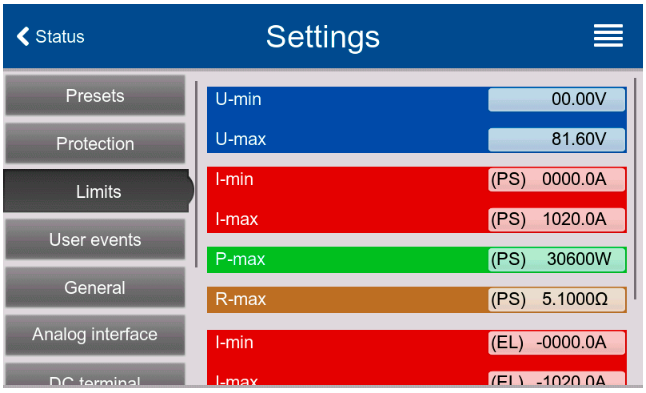
2.3.1.7 Menu "HMI Setup"

These settings refer exclusively to the control panel (HMI).

Group	Parameters & description
Language	Selection of the display language (default: English)
Sound	**Key sound**
	Activates or deactivates sounds when touching a touch area in the display. It can acoustically signal that the action has been accepted.
	Alarm sound
	Activates or deactivates the additional acoustic signal of an alarm or user defined event which has been set to **Action = Alarm.** Also see *«3.5. Alarms and monitoring»* in the installation manual..
Clock	Internal clock and date setup
Backlight	**Backlight off after 60s**
	The choice here is whether the backlight remains permanently on (default) or if it should go off after 60 s, if there was no input via touch screen or knob. As soon as there is input, the backlight returns automatically. Furthermore, the backlight intensity can be adjusted here.
Lock	See *«3.4.5 Locking the control panel (HMI)»* and *«3.4.6 Locking the adjustment limits and user profiles»* in the installation manual.

2.3.2 Adjustment limits

⚠	Adjustment limits are only effective on the related set values, no matter if using manual adjustment or remote control setting!



Defaults are that all set values (U, I, P, R) are adjustable from 0 to 102%, except for the voltage with the 60 V model which is adjustable to 100%.

The full range may be obstructive in some cases, especially for protection of applications against overvoltage. Therefore upper and lower limits for current (I) and voltage (U) can be set separately, which then limit the range of the adjustable set values.

For power (P) and resistance (R) only upper value limits can be set.

► How to configure the adjustment limits

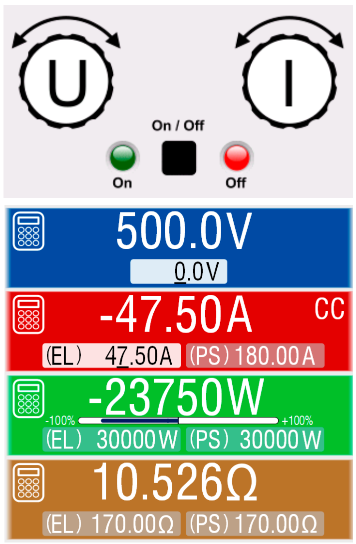
1. While the DC terminal is switched off, tap Settings on the main screen.
2. Tap on group **Limits** on the left side to open the list of limits. They are grouped and colored for distinction. Values are adjusted by tapping on them, in a window popping up with a numeric pad. Values further down in the list are accessed by swiping the list up.
3. Adjust the desired value and submit with Enter.

!	*The adjustment limits are coupled to the set values. It means, that the upper limit may not be set lower than the corresponding set value. Example: If you wish to set the limit for the power set value (P-max) to 6000 W while the currently adjusted power set value is 8000 W, then the set value would first have to be reduced to 6000 W or less, in order to set P-max down to 6000 W.*

2.3.3 Changing the operating mode

In general, the manual operation of the device distinguishes between three operating modes: U/I, U/P and U/R. They are tied to set value input using the rotary knobs or the on-screen numeric pad. The current assignment can be switched anytime if you want to adjust a set value which is currently not assigned to any of the knobs.

► How to change the operating mode (two options)



1. Unless the device is in remote control or the panel is locked, tap on the depiction of the right-hand knob on the screen (see the figure to the right) to change its assignment between I, P and R (if resistance mode is activated) for source mode (PS) and after that to I, P and R for sink mode (EL). The knob will display accordingly, with letters.
2. Directly tap on the colored areas with the set values, like shown in the figure to the right. The set value field, when inverted, indicates the assignment to the knob. In the example in the figure it has U and I (sink) assigned, which means U/I mode.

Depending on the selection, the right rotary knob will be assigned different setting values, the left knob is always assigned to the voltage.

!	*In order to change the other values, like P or R while U/I is active, and without switching the assignment all the time, direct input can be used.*

The actual operating mode, which is only indicated while the DC terminal is switched on, solely depends only on the set values. For more information see *«2.2 Operating modes»*.

2.3.4 Recording to USB stick (logging)

Device data can be recorded to a USB stick (USB 3.0 is supported, but not all memory sizes) anytime. For specifications of the USB stick and the generated log files refer to section *«1.9.6.5. USB port (front side)»* in the installation manual.

The logging stores files of CSV format on the stick where the layout of the log data is the same as when logging via PC with software EA Power Control. The advantage of USB logging over PC logging is the mobility and that no PC is required. The logging feature just has to be activated and configured in the Settings.

2.3.4.1 Restrictions

USB logging in this form isn't available or automatically deactivated if the battery test logging in the battery test is activated or the PV function **EN50530** is configured and loaded.

2.3.4.2 Configuration

Also see section *2.3.1.6*. After USB logging has been enabled and the parameters **Logging interval** and **Start/Stop** have been set, logging can be started anytime after leaving the **Settings** menu.

Furthermore see section *2.3.1.1*. There are additional settings for the CSV file itself as generated by the USB logging features. You can switch the column separator format between german/european standard (**Default**) or US american standard (**US**). The other option is used to deactivate the physical unit that is added by default to every set/actual value in the log file. Deactivating this option simplifies the CSV file processing in MS Excel or similar tools.

2.3.4.3 Handling (start/stop)

With setting **Start/stop** to **At DC on/off** logging will start each time the DC terminal of the device is switched on, no matter if manually with the front button **On/Off** or remotely via analog or digital interface. With setting **Manual** it's different. Logging is then started and stopped only in the quick menu (see the figure to the right).

Button starts logging manually and changed to , which is for manual stop.

Soon after logging has been started, the symbol indicates the ongoing logging action. In case there is an error while logging, such as the USB stick is full or removed, it will be indicated by another symbol (ERR). After every manual stop or switching the DC terminal off the logging is stopped and the log file closed.

2.3.4.4 USB logging file format

Type: text file in german/european or US american CSV format (depending on the selected setting)

Layout (default german format shown):

	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O	P
1	U set	U actual	I set (PS)	I actual	P set (PS)	P actual	R set (PS)	R actual	R mode	I set (EL)	P set (EL)	R set (EL)	Output/Input	Device mode	Error	Time
2	0,0V	50,0V	5,00A	-30,00A	15000W	-1500W	N/A	N/A	OFF	50,00A	15000W	N/A	ON	NONE	NONE	00:00:00,354
3	0,0V	50,0V	5,00A	-40,00A	15000W	-2000W	N/A	N/A	OFF	50,00A	15000W	N/A	ON	NONE	NONE	00:00:00,854
4	0,0V	50,0V	5,00A	-20,00A	15000W	-1000W	N/A	N/A	OFF	50,00A	15000W	N/A	ON	NONE	NONE	00:00:01,354
5	0,0V	50,0V	5,00A	0,00A	15000W	0W	N/A	N/A	OFF	50,00A	15000W	N/A	OFF	NONE	NONE	00:00:01,854

Legend:

U set: Voltage set value

U actual / I actual / P actual / R actual: Actual values

I set (PS) / P set (PS) / R set (PS): Set values I, P and R, belonging to source mode (PS)

I set (EL) / P set (EL) / R set (EL): Set values I, P and R, belonging to sink mode (EL)

R mode: Resistance mode activated/deactivated (also called 'UIR mode')

Output/Input: State of the DC terminal

Device mode: Actual control mode (also see *«2.2 Operating modes»*)

Error: Device alarms

Time: Elapsed time since logging start

Important to know:

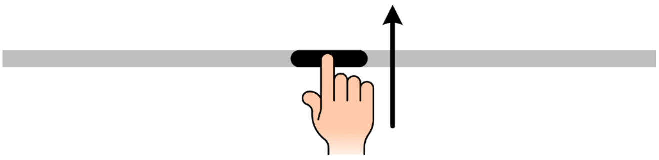
- R set and R actual are only recorded if "UIR mode" is active (refer to section *2.3.3*)
- Unlike the logging on PC, every log start here creates a new log file with a counter in the file name, starting generally with 1, but minding existing files

2.3.4.5 Special notes and limitations

- Max. log file size (due to FAT32 formatting): 4 GB
- Max. number of log files in folder HMI_FILES: 1024
- With setting **Start/stop** being **At DC on/off**, the logging will also stop on alarms or events with action **Alarm**, because they switch off the DC terminal
- With setting **Start/stop** being **Manual**, the device will continue to log even on occurring alarms, so this mode can be used to determine the period of temporary alarms like OT or PF

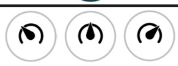
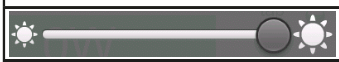
2.3.5 The quick menu

The device offers a quick menu which allows for the quick access to often used features and modes being switched on or off in the “Settings” menu. It can be opened by swiping up from the bottom screen edge or tapping the bar:



Overview:

Tapping a button activates or deactivates the feature. Buttons with black on white indicate an activated feature:

Symbol	Belongs to	Meaning or function
	USB logging	USB logging is running (the symbol is only available when USB logging has been activated in menu “Settings”)
M	Master-slave	Master-slave activated, device is master
S	Master-slave	Master-slave activated, device is slave
Off	Master-slave	Master-slave deactivated
Ω	Resistance mode	R mode = on
	HMI	Alarm sound = on
	HMI	Key sound = on
	HMI	Opens the graph screen
	Operation modes	Switches voltage controller speed between **Slow**, **Normal** (default) and **Fast** (see section *2.2.7*)
	HMI	Adjust backlight intensity
Menu	HMI	Opens the main menu

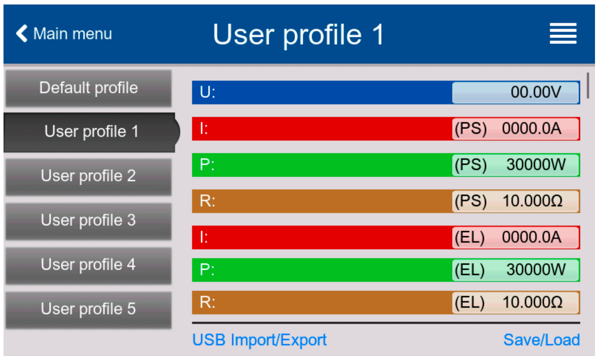
2.3.6 Loading and saving user profiles

The menu **Profiles** serves to select between a default profile and up to 5 user profiles. A profile is a collection of all settings and set values. Upon delivery or after a factory reset, all 6 profiles have the same settings and all set values are 0. Values adjusted on the main screen or anywhere else belong to a working profile which can be saved to one of the 5 user profiles. These user profiles or the default profile can then be switched. The default profile is read-only.

The purpose of a profile is to load a set of set values, settings limits and monitoring thresholds quickly without having to readjust these. As all HMI settings are saved in the profile, including language, a profile change can also be accompanied by a change in HMI language.

On calling up the menu page and selecting a profile the most important settings can be seen, but not changed.

► How to save the current values and settings as a user profile



1. While the DC terminal is switched off, tap on touch area 

on the main screen.
2. In the main menu tap on **Profiles**.
3. In the next screen (see the example to the right) choose between user profiles 1-5, which will show the profile's stored settings for your verification.
4. Tap on **Save/Load** and save the settings into the user profile in the coming up requester **Save profile?** with **Save**.

!	*All user profiles also allow to just edit some settings or values stored in the profile. When doing so, the changes either need to be saved to the profile with "Save changes" or discarded with "Cancel" before the profile can be loaded.*

Loading a user profile works the same way, but in the requester you would then tap **Load** under **Load profile?**. Alternatively, you may import the profile or export it as file to a USB stick with **USB Import/Export**.

► How to edit a user profile

1. While the DC terminal is switched off, tap on touch area 

on the main screen.
2. In the main menu tap on **Profiles**.
3. In the next screen choose the user profile to edit, which will show the profile's stored settings for your verification.
4. Tape on the values you want to edit. As soon as any values has been changed, the button **Save/Load** will turn into **Save changes**.
5. Tap on **Save changes** to save the changes into the user profile. At this point, the profile's values are not effective yet.
6. Optional: in order to submit the changes in the user profile to the working profile, tap on **Save/Load** and in the requester **Load profile?** choose **Load**.

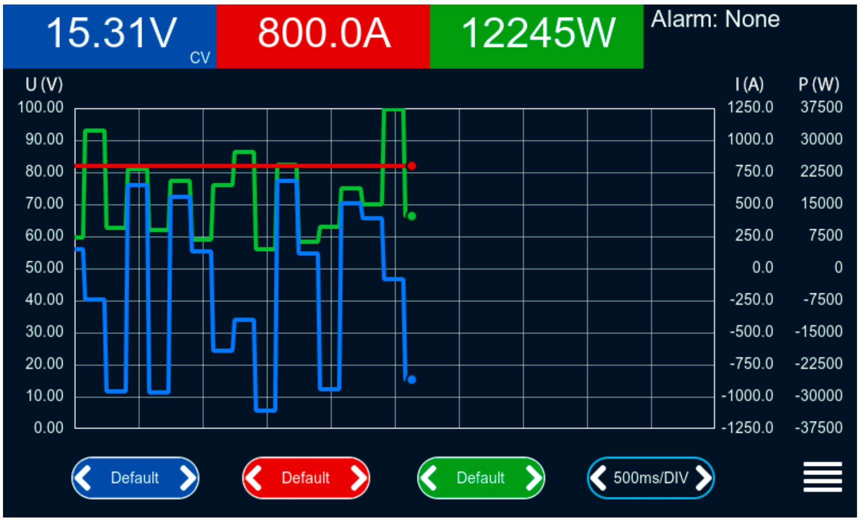
2.3.7 The graph

The devices feature a manually callable, HMI operated visual depiction of the temporal run of the actual values of voltage, current and power, called the graph. However, it isn't a recording feature. For data recording in the background there is still the USB logging feature (see section *2.3.4*).

In normal operation the graph can be called up anytime via the quick menu, whilst in function generator operation it's called up by an extra screen button. When shown, it completely fills the screen.

⚠	Limited control options available while the graph screen is shown! For safety reasons, however, it's possible to switch off the DC terminal anytime via button On/Off.

Overview:



Controls:

- Tapping the **middle** of the three red/green/blue touch areas deactivates/activate the corresponding plot
- Tapping the **sides** (arrows left/right) of the red/green/blue touch areas increases/decreases the vertical scaling
- Tapping the **sides** (arrows left/right) of the black touch area increases/decreases the horizontal scaling
- Swiping on the three scales (Y axis) moves them up or down
- Tapping the menu touch area ( ) exits the graph screen anytime

2.4 Remote control

2.4.1 General

Remote control is possible via one of the built-in interfaces (analog, USB, Ethernet) or via one of the optional interface modules. One of the digital interfaces is the master-slave bus.

Important here is that only the analog or one of the digital interfaces can be in control. It means that if an attempt was made to switch to remote control via the digital interface whilst analog remote control is active (pin REMOTE = LOW) the device would report an error via the digital interface. In the opposite direction, a switch-over via pin REMOTE would be ignored. However, status monitoring and reading of values are always possible.

2.4.2 Control locations

Control locations are those locations from where the device can be controlled. Essentially there are two: at the device (manual operation) and external (remote control). The following locations are defined:

Displayed location	Description
Remote: None	If neither of the other locations is displayed then manual control is active and access from the analog and digital interfaces is allowed.
Remote: <interface_name>	Remote control via any interface is active
Local	Remote control is locked, only manual operation is allowed.

Remote control may be allowed or inhibited using the setting **Allow remote control** (see *«2.3.1.1 Sub menu "Settings"»*). In inhibited condition the status **Local** will be displayed top right. Activating the inhibit can be useful if the device is remotely controlled by software or some electronic device, but it's required to make adjustments on the device or deal with an emergency.

Activating condition **Local** causes the following:

- If remote control via the digital interface is active (e. g. **Remote: USB**), then it's immediately terminated and in order to continue remote control once **Local** is no longer active, it has to be reactivated at the PC
- If remote control via the analog interface is active (**Remote: Analog**), then it's temporarily interrupted until remote control is allowed again by deactivating **Local**, because pin REMOTE continues to signal "remote control = on", unless this has been changed during the **Local** period.

2.4.3 Remote control via a digital interface

2.4.3.1 Selecting an interface

In addition to the built-in USB and Ethernet ports, all models of this series support the following optionally available interface modules:

Short ID	Type	Ports	Description*
IF-AB-CANO	CANopen	1	CANopen slave with generic EDS
IF-AB-RS232	RS232	1	Standard RS232, serial
IF-AB-PBUS	Profibus	1	Profibus DP-V1 slave
IF-AB-PNET1P	ProfiNet	1	Profinet DP-V1 slave
IF-AB-PNET2P	ProfiNet	2	Profinet DP-V1 slave, with switch
IF-AB-CAN	CAN	1	CAN 2.0 A / 2.0 B
IF-AB-ECT	EtherCAT	2	Standard EtherCAT slave with CoE
IF-AB-MBUS1P	ModBus TCP	1	ModBus TCP protocol via Ethernet
IF-AB-MBUS2P	ModBus TCP	2	ModBus TCP protocol via Ethernet

* For technical details of the various modules see the extra documentation "Programming Guide Modbus & SCPI"

2.4.3.2 Programming

Programming details for the rear interfaces, the communication protocols etc. are to be found in the documentation "Programming guide ModBus & SCPI" which is supplied on the included USB stick or which is available as download from the manufacturer's website.

2.4.3.3 Interface monitoring

Interface monitoring is an HMI configurable functionality. Its goal is to monitor (or supervise) the digital communication line between the device and a superior control unit, such as PC or PLC, and to ensure that the device wouldn't continue working uncontrolled in case the communication line fails. A failing line can mean that it's either physically interrupted (damaged cable, bad contact, cable pulled) or the interface port inside the device hangs.

The monitoring is always only valid for one of the digital interfaces, the one being used for remote control. It thus means that the monitoring can become temporarily inactive when the device leaves remote control. It's furthermore based on a user-definable timeout which would run out if not at least one message is sent to the device within the given time frame. After every message, the timeout would start again and reset with the next incoming message. In case it runs out, the following reaction of the device is defined:

- Exit remote control
- In case the DC terminal is switched on, it would either switch the DC terminal off or leave it on, as defined by the parameter **DC terminal -> State after remote** (see section *2.3.1.1*)

Notes for the operation:

- The timeout of the monitoring can be changed anytime via remote control; the new value would only be valid after the current timeout has elapsed
- The interface monitoring doesn't deactivate the Ethernet connection timeout (see section *2.3.1.6*), so these two timeouts can overlap

2.4.4 Remote control via the analog interface

2.4.4.1 General

The galvanically isolated, 15-pole analog interface, as built-in and below referenced in short form as AI, is located on the rear side of the device offers the following possibilities:

- Remote control of current, voltage, power and resistance
- Remote status monitoring (CV, DC terminal)
- Remote alarm monitoring (OT, OVP, PF, OCP, OPP)
- Remote monitoring of actual values
- Remote on/off switching of the DC terminal

Setting the **three** set values of voltage, current and power via the analog interface must always be done concurrently. It means, for example, that the voltage can't be given via the AI and current and power set by the rotary knobs or vice versa. The internal resistance set value can additionally be adjusted. Contrary to manual adjustment or via digital interface, the analog interface doesn't offer separate set values of power and current for the source and sink mode.

Analog set values can be supplied by an external voltage or generated from the reference voltage on pin 3. As soon as remote control via the analog interface is activated, the displayed set values will be those provided by the interface. The AI can be operated in the common voltage ranges 0...5 V and 0...10 V, both representing 0...100% of the nominal value. The selection of the voltage range can be done in the device setup. See *«2.3.1 Configuration via the menu»* for details. The reference voltage sent out from pin 3 (VREF) will be adapted accordingly:

0-5V: Reference voltage = 5 V, 0...5 V set value (VSEL, CSEL, PSEL, RSEL) correspond to 0...100% of the rated value or R_{Min}...R_{Max}, 0...100% of the actual values correspond to 0...5 V at the outputs CMON and VMON, at least as long these two pins are still configured for the default (see *«2.3.1 Configuration via the menu»*).

0-10V: Reference voltage = 10 V, 0...10 V set value (VSEL, CSEL, PSEL, RSEL) correspond to 0...100% of the rated value or R_{Min}...R_{Max}, 0...100% of the actual values correspond to 0...10 V at the outputs CMON and VMON, at least as long these two pins are still configured for the default (see *«2.3.1 Configuration via the menu»*).

All set values are always additionally limited to the corresponding adjustment limits (U-max, I-max etc.), which would clip setting excess values for the DC terminal. Also see *«2.3.2 Adjustment limits»*.

Before you begin, please read these important notes about the use of the interface:

!	*After powering the device and during the start phase the AI signals undefined statuses on the output pins. Those must be ignored until it's ready to work.*

- Analog remote control of the device must be activated by switching pin REMOTE (5) first. Only exception is pin REM-SB, which can be used independently
- Before the hardware is connected that will control the analog interface, it shall be checked that it can't provide voltage to the pins higher than specified
- Set value inputs, such as VSEL, CSEL, PSEL and RSEL (if R mode is activated), must not be left unconnected (i.e. floating) during analog remote control. In case any of the set values is not used for adjustment, it can be tied to a defined level or connected to pin VREF (solder bridge or different), so it gives 100%
- Switching between sink and source mode can only be done with the voltage level on pin VSEL. Also see example d) in section *2.4.4.7*.

2.4.4.2 Acknowledging device alarms

In case of a device alarm occurring during remote control via analog interface, the DC terminal will be switched off the same way as in manual control. The device would indicate an alarm (see section *3.5* in the installation manual) in the front display and, if activated, acoustically and also signal most of them on the analog interface. Which alarms actually are signaled can be set up in the device configuration menu (see *«2.3.1.1 Sub menu "Settings"»*).

Most device alarms have to be acknowledged (also see *«3.5.2. Device alarm and event handling»* in the installation manual*)*. Acknowledgment is done with pin REM-SB switching the DC terminal off and on again, which represents a HIGH-LOW-HIGH signal (min. 50ms for LOW), when using the default level setting for this pin.

There is one **exception**: the SOVP (Safety OVP) alarm, which is only featured with the 60 V model of this series. It can't be acknowledged and requires to power-cycle the device. It can be monitored via the analog interface and would be indicated by the alarms PF and OVP being signaled at the same time, so it would require to select the alarm indication on pin 6 to at least signal PF and for pin 14 to signal OVP in any of the combinations.

2.4.4.3 Analog interface specification

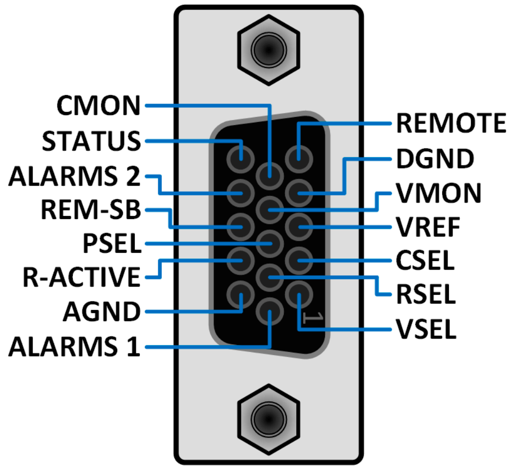
Pin	Name	Type (1	Description	Default levels	Electrical specifications
1	**VSEL**	AI	Voltage set value	0...10 V or 0...5 V correspond to 0..100% of U_{Nom}	Accuracy 0-5 V range: < 0.4% (5 Accuracy 0-10 V range: < 0.2% (5 Input impedance R_i >40 k...100 k
2	**CSEL**	AI	Current set value (source & sink)	0...10 V or 0...5 V correspond to 0..100% of I_{Nom}	
3	**VREF**	AO	Reference voltage	10 V or 5 V	Tolerance < 0.2% at I_{max} = +5 mA Short-circuit-proof against AGND
4	**DGND**	POT	Ground for all digital signals		For control and status signals
5	**REMOTE**	DI	Switches between manual and remote control	Remote = LOW, U_{Low} <1 V Manual = HIGH, U_{High} >4 V Manual, if pin not wired	Voltage range = 0...30 V I_{Max} = -1 mA at 5 V $U_{LOW\ to\ HIGH\ typ.}$ = 3 V Rec'd sender: Open collector against DGND
6	**ALARMS 1**	DO	Overheating /power fail alarm	Alarm = HIGH, U_{High} > 4 V No alarm = LOW, U_{Low} <1 V	Quasi open collector with pull-up against Vcc (2 With 5 V on the pin max. flow +1 mA I_{Max} = -10 mA at U_{CE} = 0,3 V U_{Max} = 30 V Short-circuit-proof against DGND
7	**RSEL**	AI	Resistance value (source & sink)	0...10 V or 0...5 V correspond to R_{Min}...R_{Max}	Accuracy 0-5 V range: < 0.4% (5 Accuracy 0-10 V range: < 0.2% (5 Input impedance R_i >40 k...100 k
8	**PSEL**	AI	Power set value (source & sink)	0...10 V or 0...5 V correspond to 0..100% of P_{Nom}	
9	**VMON**	AO	Actual voltage	0...10 V or 0...5 V correspond to 0..100% of U_{Nom}	Accuracy 0-5 V range: < 0.4% (5 Accuracy 0-10 V range: < 0.2% (5 at I_{Max} = +2 mA Short-circuit-proof against AGND
10	**CMON**	AO	Actual current	0...10 V or 0...5 V correspond to 0..100% of I_{Nom}	
11	**AGND**	POT	Ground for all analog signals		For xSEL, xMON and VREF
12	**R-ACTIVE**	DI	R mode on / off	On= LOW, U_{Low} <1 V Off = HIGH, U_{High} >4 V Off, if pin not wired	Voltage range = 0...30 V I_{Max} = -1 mA at 5 V $U_{LOW\ to\ HIGH\ typ.}$ = 3 V Rec'd sender: Open collector against DGND
13	**REM-SB**	DI	DC terminal OFF (DC terminal ON) (ACK alarms (4))	Off = LOW, U_{Low} <1 V On = HIGH, U_{High} >4 V On, if pin not wired	Voltage range = 0...30 V I_{Max} = +1 mA at 5 V Rec'd sender: Open collector against DGND
14	**ALARMS 2**	DO	Overvoltage alarm Overcurrent alarm Overpower alarm	Alarm = HIGH, U_{High} > 4 V No alarm = LOW, U_{Low} <1 V	Quasi open collector with pull-up against Vcc (2 With 5 V on the pin max. flow +1 mA I_{Max} = -10 mA at U_{CE} = 0,3 V, U_{Max} = 30 V Short-circuit-proof against DGND
15	**STATUS (3**	DO	Constant voltage control active	CV = LOW, U_{Low} <1 V CC/CP/CR = HIGH, U_{High} >4 V	
			DC terminal	Off = LOW, U_{Low} <1 V On = HIGH, U_{High} >4 V	

(1 AI = Analog Input, AO = Analog Output, DI = Digital Input, DO = Digital Output, POT = Potential
(2 Internal Vcc approx. 10 V
(3 Only one of both signals possible, see section *2.3.1.1*
(4 Only during remote control
(5 The error of a set value input adds to the general error of the related value on the DC terminal of the device

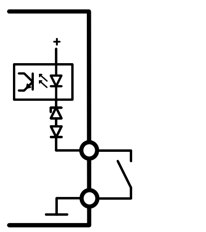
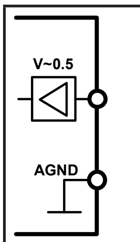
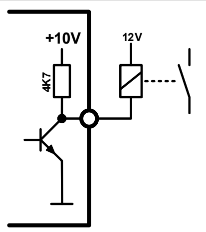
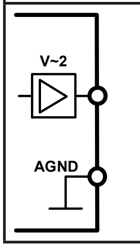
2.4.4.4 Resolution

The analog interface is internally sampled and processed by a digital micro-controller. This causes a limited resolution of analog steps. The effective resolution is the same for set values (VSEL etc.) and actual values (VMON/CMON). It's 26214 steps for 0...100%, when working in the 10 V range. In the 5 V range this resolution halves. Due to tolerances, the truly achievable resolution can be slightly lower.

2.4.4.5 Overview of the D-sub socket

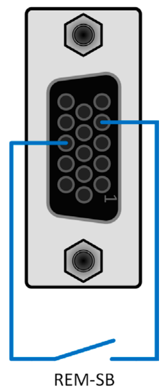


2.4.4.6 Simplified diagram of the pins

	**Digital Input (DI)** It requires to use a switch with low resistance (relay, switch, circuit breaker etc.) in order to send a clean signal to the DGND.		**Analog Input (AI)** High resistance input (impedance >40 kΩ) for an operation amplifier circuit.
	**Digital Output (DO)** A quasi open collector, realized as high resistance pull-up against the internal supply. In condition LOW it can't drive any load, only sink small current, as shown in the diagram with a relay as example.		**Analog Output (AO)** Output from an operation amplifier circuit, low impedance. See the specifications table above.

2.4.4.7 Application examples

a) Switching the DC terminal with pin REM-SB



!	*A digital output, e.g. from a PLC, may be unable to cleanly pull down the pin as it may not be of sufficiently low resistance. Check the specification of the controlling application. Also see the pin diagrams above.*

In analog remote control, pin REM-SB is used to switch the DC terminal of the device on and off. This function is also available without analog remote control being active and can, on one hand, block the DC terminal from being switched on in manual or digital remote control and, on the other hand, the pin can switch the DC terminal on or off, but not standalone. See below at **Remote control has not been activated**.

⚠	REM-SB cannot serve as a safety stop switch to securely deactivate the DC terminal in case of emergency! For that an external emergency stop system is required.

It's recommended that a low resistance contact such as a switch, relay or transistor is used to switch the pin to ground (DGND).

Following situations can occur:

- **Remote control has been activated**

During remote control via analog interface, only pin REM-SB determines the states of the DC terminal, according to the level definitions in section *2.4.4.3*. The logical function and the default levels can be inverted by a parameter in the setup menu of the device. See section *2.3.1.1*.

!	*If the pin is unconnected or the connected contact is open, the pin will be HIGH. With setting "Analog interface" -> "REM-SB level" being set to "Normal", it requests to switch the DC terminal on. So when activating remote control, the DC terminal will instantly switch on.*

- **Remote control has not been activated**

In this mode of operation pin REM-SB can serve as lock, preventing the DC terminal from being switched on by any means. This results in following possible situations:

DC terminal	+	Level on pin REM-SB	+	Parameter „REM-SB Level“	→	Behavior
is off	+	HIGH	+	Normal	→	The DC terminal isn’t locked. It can be switched on by pushbutton “On/Off” (front panel) or via command from digital interface.
		LOW	+	Inverted		
	+	HIGH	+	Inverted	→	The DC terminal is locked. It can’t be switched on by pushbutton “On/Off” (front panel) or via command from digital interface. When trying to switch on, the device won’t react, but generate a requester in the display or, in remote control, return a communication error.
		LOW	+	Normal		

In case the DC terminal is already switched on, toggling the pin will switch the DC terminal off, similar to what it does in analog remote control:

DC terminal	+	Level on pin REM-SB	+	Parameter „REM-SB Level“	→	Behavior
is on	+	HIGH	+	Normal	→	The DC terminal remains on, nothing is locked. It can be switched on or off by pushbutton or digital command.
		LOW	+	Inverted		
	+	HIGH	+	Inverted	→	The DC terminal will be switched off and locked. Later it can be switched on again by toggling the pin. During lock, pushbutton or digital command can delete the request to switch on by pin.
		LOW	+	Normal		

b) Remote control of current and power (source mode)

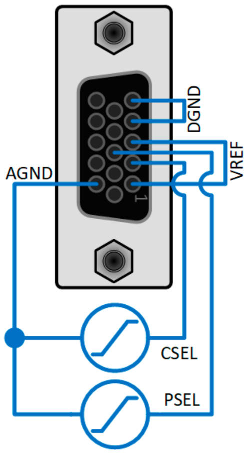
Requires remote control to be activated (pin REMOTE = LOW)

The set values PSEL and CSEL are generated from, for example, the reference voltage VREF, using potentiometers for each. Hence the power supply can selectively work in current limiting or power limiting mode. According to the specification of max. 5 mA load for the VREF output, potentiometers of at least 10 kΩ must be used.

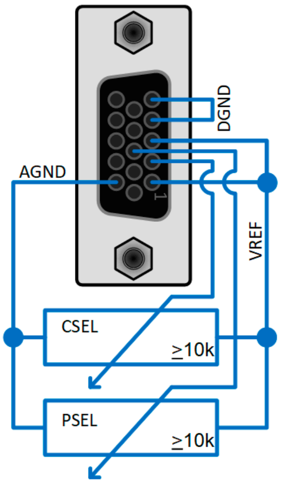
The voltage set value VSEL is directly connected to VREF and will be permanently at 100%. This also means that the device can only work in source mode.

If the control voltage is fed in from an external source it’s necessary to consider the input voltage ranges for set values (0...5 V oder 0...10 V).

!	*When using the voltage range 0...5 V the effective resolution of set values and actual values halves.*



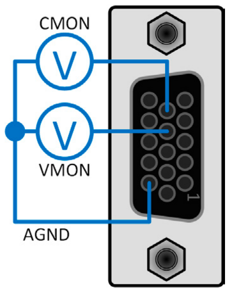
Example with external voltage source



Example with potentiometers

c) Reading actual values

The AI provides the DC terminal values as current and voltage monitor. These can be read using a standard multimeter or similar.



d) Switching between source and sink mode

You can also switch between both modes when remotely controlling the device with the AI. This is done using the voltage set value (VSEL), which then must not be tied to a fixed potential, like shown in example b). Rules:

- If the voltage set value on VSEL (in %, not the level) becomes higher than the actual voltage on the DC terminal, the device will switch to sink mode, no matter if the voltage on the DC terminal is generated by the device or from external
- If the voltage set value becomes lower than the actual voltage, the device will switch to source mode.

e) Determining the actual operation mode between source and sink

The limited number of pins on the AI doesn't allow for a separate signal to indicate sink or source mode. There are basically two ways to determine the actual mode in analog remote control:

- Compare the actual voltage output (VMON) with VSEL and also read the CMON signal -> if the level of VMON is higher than VSEL and CMON isn't zero, then the device is in sink mode, otherwise if VMON is equal to or lower than VSEL, it's in source mode, no matter what the level of CMON is
- Configure pins 9 (VMON) and 10 (CMON), as described in section *2.3.1*, for **Mode A** or **Mode B** and read both pins; when DC current is flowing in any of both directions, one of the pins will indicate with a level > 0 V.

2.4.4.8 Analog interface priority

A new functionality, available for all 10000 series devices with analog interface and from firmware KE 3.10 and HMI 4.09, allows the user to prioritize the analog interface over other remote control interfaces. The rule was and is that no interface, analog or digital, is superior to another in regard of the remote control state. It means, that when a device would be in remote control by any digital interface and the remote control is going to be switched over to analog interface, it would require to leave the digital remote control state first via a specific command sent via the interface in control.

With this feature, when activated (see section *2.3.1.1*), the analog interface can take over remote control anytime, except when the condition **Local** is set. In the moment of the switchover, the set values and the DC terminal status, as given by the pins of the analog interface, would become effective immediately. In the contrary, leaving analog remote control (pin: REMOTE) would neither return the device into the prior state of digital remote control, nor restore the set values and DC condition as they were before. Leaving remote control always keeps the last set of set values, while the DC terminal condition is determined by the parameter **State after remote** (see section *2.3.1.1*).

3. The function generator

3.1 Introduction

The built-in **function generator** (short: **FG**) is able to create various signal forms and apply these to the set value of either voltage or current.

The standard functions are based on an **arbitrary generator** and directly accessible and configurable using manual control. In remote control, the fully customizable arbitrary generator replicates these functions with sequence points containing 8 parameters each.

Other functions, such as IU, PV or FC are based on an **XY generator** that works with a table of 4096 values which are either loaded from a USB stick or calculated based upon adjustable parameters.

The following functions are retrievable, configurable and controllable:

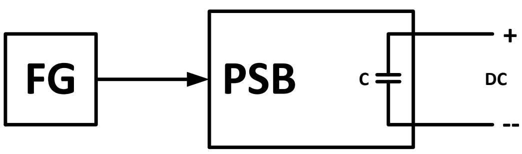
Function	Short description
Sine	Sine wave generation with adjustable amplitude, offset and frequency
Triangle	Triangular wave signal generation with adjustable amplitude, offset, rise and fall times
Rectangular	Rectangular wave signal generation with adjustable amplitude, offset and duty cycle
Trapezoid	Trapezoidal wave signal generation with adjustable amplitude, offset, rise time, pulse time, fall time, idle time
DIN 40839	Simulated automobile engine start curve according to DIN 40839 / EN ISO 7637, split into 5 curve sequences, each with a start voltage, final voltage and time
Arbitrary	Generation of a process with up to 99 freely configurable curve points, each with a start and end value (AC/DC), start and end frequency, phase angle and duration
Ramp	Generation of a linear rise or fall ramp with start and end values and time before and after the ramp
XY table	XY generator, USB stick loadable current curve (table, CSV)
PV table (PS) **PV EN50530** **FC table (PS)**	Functions to simulate a solar panel (PV function), also according to EN 50530, or fuel cell (FC function), both with table calculation based upon adjustable parameters
Battery test	Battery charge and discharge test with constant or pulsed current, along with Ah, Wh and time counters
MPP tracking	Simulation of the characteristic tracking behavior of solar inverters when seeking to find the maximum power point (MPP) when being connected to typical sources such as solar panels

3.2 General

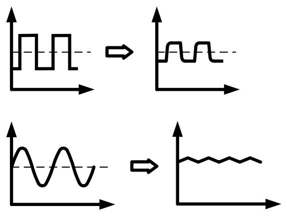
3.2.1 Principle

The device features a built-in function generator (short: FG), but the entire unit can't be considered as a high power function generator, because its power stages are only post-connected to the FG. Primarily in source mode, the typical characteristics of a voltage and current source remain. Rise and fall times, caused by capacitor charge/discharge, affect the resulting signal on the DC terminal. While the FG is able to generate a sine wave with 10000 Hz, the device will never be able to follow the generated signal 1:1. Source and sink mode will slightly differ from each other regarding the results, while the sink mode will be generally better, because primarily focused on current.

Depiction of principle:



Effect of the DC power stages on functions:



The resulting wave on the DC terminal heavily depends on the frequency resp. period of the selected wave, its amplitude and also the voltage rating of the device. The effect of the capacities on the wave can be partially compensated. In source mode and when running voltage dynamics to which the capacities have the biggest impact on it can help to put an additional load to the DC terminal in order to decrease rise and fall times. This extra load has a positive impact on periodic functions like rectangle or sine wave.

3.2.2 Resolution

Amplitudes generated by the arbitrary generator have an effective resolution of approx. 52428 steps between 0 and 100% of the rated range. If the amplitude is very low and the time long, the device would generate less steps and set multiple identical values after another, generating a staircase effect.

3.2.3 Possible technical complications

Operation of switching mode power supplies as a voltage source can, when applying a function to the output voltage, lead to damage of the output capacitors due to continuous charging/discharging which causes overheating.

3.2.4 Method of operation

In order to understand how the function generator works and how the values interact, the following should be observed:

The device always works with the three set values U, I and P, also in function generator mode.

The selected function can be used on one set value, U or I, while the other two values are constant and have a limiting effect. Example: in sink mode, a source with 100 V is connected and the sine function applied to the current with an amplitude of 80 A and offset 80 A. The function generator would create a sine wave progression of current between 0 A (min) and 160 A (max), which will result in an input power between 0 W (min) and 16000 W (max). But in case the power would be limited to 12000 W the current would be limited to 120 A and if probed with an oscilloscope it could be viewed being truncated at 120 A and never reach the peak of 160 A.

For an even better understanding of how the device works in dynamic operation, read the following:

- The device also has an integrated electronic load, also called sink, which is supposed to discharge the capacities on the DC terminal of the device when running dynamic voltage changes in source mode, i.e higher voltage to lower voltage. This requires certain current and power settings, which can and should be adjusted for almost every function described below (values “I (EL)” and “P (EL)”). For safety reasons, the value “I (EL)” is always set to 0 after selecting a function for configuration, which deactivates the sink mode.
- The sink current, adjustable as “I (EL)”, when being set to > 0 would load an external source, perhaps also discharge capacities in this source and thus this current setting has to be chosen carefully, because it also affects the necessary cross section of cables. Recommendation: set “I (EL)“ to at least I_{Peak} of the resulting curve or higher.

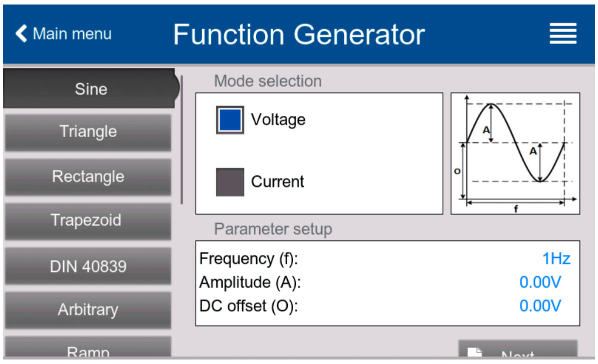
Master-slave systems have further characteristics which have to be considered:

At the end of the configuration, after the function has been loaded and the screen shows the main view of the function generator, there are adjustable set values, the so-called “U/I/P limits”. These limits are transferred as set values to all slave units of a master-slave system. It’s required to carefully configure these limits, so the MS system can work as expected and the slaves wouldn’t impact the function run in a negative way.

3.3 Manual operation

3.3.1 Function selection and control

All the functions listed in section *3.1* can be accessed on the touch screen, configured and controlled. Selection and configuration are only possible while the DC terminal is switched off.



► How to select a function and adjust parameters

1. While the DC terminal is switched off tap on touch area Func Gen on the main screen.

2. In the menu, select the desired function by tapping on the list on the left-hand side. Depending on the selected function, you will have to choose to either apply the function to **Voltage** or **Current**.

3. Adjust the parameters as you desire and then tap on Next.

4. In the next screen, adjust the overall limits of voltage, current and power, then continue with Next.

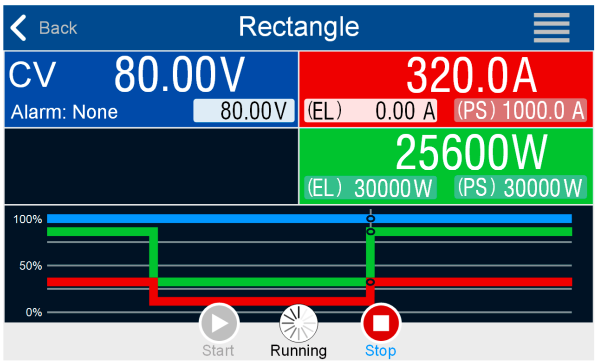
5. As the last part of the configuration, global set values have to be defined which are considered as static values and come into effect before and after the function run. Correct setup here is important, <u>especially when running the function on a master device of a master-slave system</u>.

> - *When intending to run a function exclusively in sink or in source mode, it's recommended to set the set values (I, P) of the opposite mode to 0.*
> - *The global limits of U, I and P become instantly active after the function has been loaded and when coming to the main screen of the function generator, because the DC terminal is then switched on automatically to settle the start situation. This can be helpful when a function shall not start at 0 V or 0 A. In case the situation requires otherwise, the static values could also be set to 0, which is otherwise not correct for a master-slave system, because the set values of the slave units would then be 0. There is a switch called "Set DC terminal only active during running function" which, when set, would prevent the automatic DC terminal switch-on after loading.*

6. Exit the configuration and enter the main function generator screen with Next.

Setting the various functions and their parameters is described below. After the function generator screen has been reached, the function is ready to run. Before and while the function is running, some global and also some function related values can be adjusted anytime.

► How to start and stop a function



1. The function can be <u>**started**</u> either by tapping on or if the DC terminal is currently switched off by pushing the "**On/Off**" button on the front.

2. The function can either be <u>**stopped**</u> by tapping on or operating the "On/Off" button. However, there is a difference:

a) The button only stops the function while the DC terminal <u>remains ON</u> with the static values in effect.

b) The "On/Off" button stops the function and switches the DC terminal off.

> *Any device alarm (power fail, overtemperature etc.), protection (OPP, OCP) or event with Action = Alarm stops the function progress automatically, switches off the DC terminal and reports the alarm.*

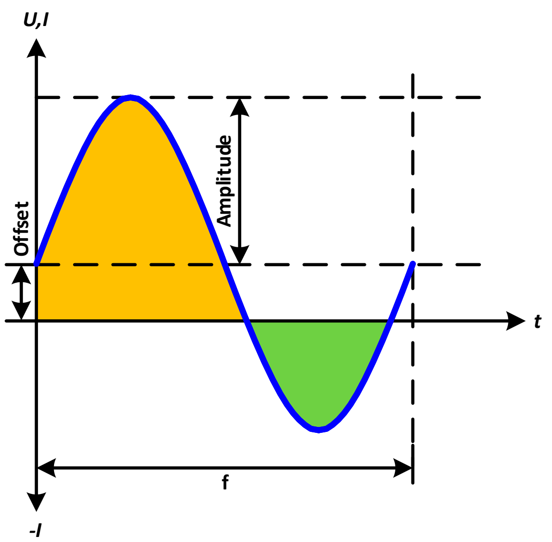
3.4 Sine wave function

Restrictions which apply particularly to this function:

- There is no preselection to which of both, source mode and sink mode, the function is applied; the settings decide whether it's "source mode only", "sink mode only" or a mixture of both
- When applying the function to the voltage, the device can only switch to and work in sink mode if the external voltage on the DC terminal is higher than the highest point (offset + amplitude) of the wave and the current setting "I (EL)" is not 0

The following parameters can be configured for a sine function:

Parameter	Range	Description
Frequency (f)	**1Hz...10000Hz**	Static frequency of the signal to be generated
Amplitude (A)	**0...**(rated value - |**Offset**|) of U or I	Amplitude of the signal to be generated
Offset (O)	**0V...**(U_{Nom} - **Amplitude**)	Offset from the zero point of the mathematical sine curve
	-(I_{Nom} - **Amplitude**)...+(I_{Nom} - **Amplitude**)	

Schematic diagram:	Application and result:
	A sine wave signal is generated and applied to the selected set value, e.g. the current (I mode). Depending on the adjusted parameters the device can apply the wave either solely to sink mode or to source mode, but also to both with automatic switchover at zero point. The diagram on the left depicts the "mixed mode" run (yellow = source mode active, green = sink mode active). While the amplitude is always an absolute value, the offset can be positive or negative (I mode only). For calculating the maximum power, the current amplitude and the offset value have to be added. Example: a voltage of 100 V is set. The parameters for the sin(I) function are: amplitude of 80 A and offset of +50 A. The resulting maximum power when reaching the highest point of the sine wave then is (80 A + 50 A) * 100 V = 13000 W for the source part and when reaching the lowest point (sink part) it will be (50.A - 80 A) * 100 V = -3000 W.

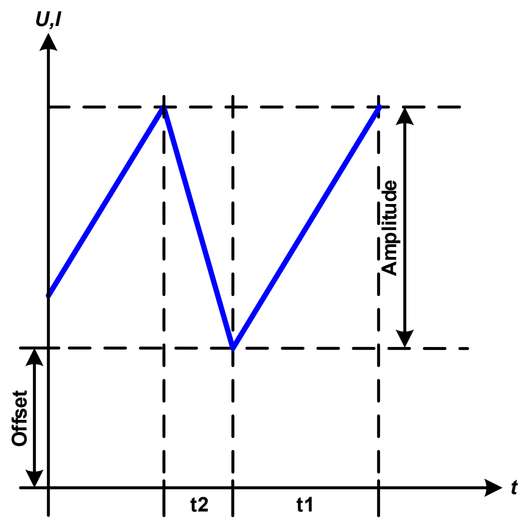
3.5 Triangular function

Restrictions which apply particularly to this function:

- There is no preselection to which of both, source mode and sink mode, the function is applied; the settings decide whether it's "source mode only", "sink mode only" or a mixture of both
- When applying the function to the voltage, the device can only switch to and work in sink mode if the external voltage on the DC terminal is higher than the highest point (offset + amplitude) of the wave and the current setting "I (EL)" is not 0

The following parameters can be configured for a triangular function:

Parameter	Range	Description
Amplitude (A)	**0...**(rated value - |**Offset**|) of U or I	Amplitude of the signal to be generated
Offset (O)	**0V...**(U_{Nom} - **Amplitude**)	Offset, based on the foot of the triangular wave
	-(I_{Nom} - **Amplitude**)...+(I_{Nom} - **Amplitude**)	
Time t1	**0.1ms...36000000ms**	Rising edge time Δt of the triangular wave signal
Time t2	**0.1ms...36000000ms**	Falling edge time Δt of the triangular wave signal

Schematic diagram:	Application and result:
	A triangular wave signal for use on the current or voltage is generated. The positive and negative slope times can be set independently. The offset shifts the signal on the Y axis. The sum of the intervals t1 and t2 gives the cycle time and its reciprocal is the frequency. Example: a frequency of 10 Hz is required and would lead to periodic duration of 100 ms. This 100 ms can be freely allocated to t1 and t2, e.g. 50 ms:50 ms (isosceles triangle) or 99.9 ms:0.1 ms (right-angled triangle or sawtooth).

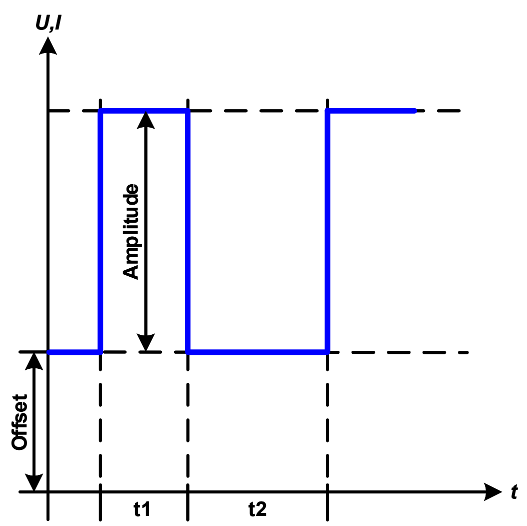
3.6 Rectangular function

Restrictions which apply particularly to this function:

- There is no preselection to which of both, source mode and sink mode, the function is applied; the settings decide whether it's “source mode only”, “sink mode only” or a mixture of both
- When applying the function to the voltage, the device can only switch to and work in sink mode if the external voltage on the DC terminal is higher than the highest point (offset + amplitude) of the wave and the current setting “I (EL)” is not 0

The following parameters can be configured for a rectangular function:

Parameter	Range	Description
Amplitude (A)	0...(rated value - |**Offset**|) of U or I	Amplitude of the signal to be generated
Offset (O)	0V...(U_{Nom} - **Amplitude**)	Offset, based on the foot of the rectangular wave
	-(I_{Nom} - **Amplitude**)...+(I_{Nom} - **Amplitude**)	
Time t1	0.1ms...36000000ms	Time (pulse width) of the upper level (amplitude)
Time t2	0.1ms...36000000ms	Time (pause width) of the lower level (offset)

Schematic diagram:	Application and result:
	A rectangular or square wave signal for use on the current or voltage is generated. The intervals t1 and t2 define how long the value of the amplitude (pulse) and how long the value of the offset (pause) are effective. The offset shifts the signal on the Y axis. Intervals t1 and t2 can be used to define a duty cycle. The sum of t1 and t2 gives the period and its reciprocal the frequency. Example: a rectangular wave signal of 25 Hz and a duty cycle of 80% are required. The sum of t1 and t2, the period, is 1/25 Hz = 40 ms. For a duty cycle of 80% the pulse time (t1) is 40 ms*0.8 = 32 ms and the pause time (t2) is 8 ms

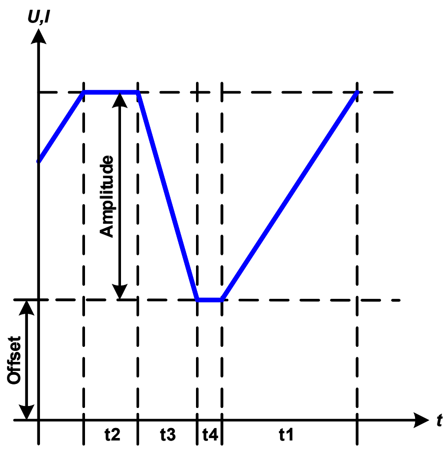
3.7 Trapezoidal function

Restrictions which apply particularly to this function:

- There is no preselection to which of both, source mode and sink mode, the function is applied; the settings decide whether it's "source mode only", "sink mode only" or a mixture of both
- When applying the function to the voltage, the device can only switch to and work in sink mode if the external voltage on the DC terminal is higher than the highest point (offset + amplitude) of the wave and the current setting "I (EL)" is not 0

The following parameters can be configured for a trapezoidal function:

Parameter	Range	Description
Amplitude (A)	0...(rated value - |**Offset**|) of U or I	Amplitude of the signal to be generated
Offset (O)	0V...(U_{Nom} - **Amplitude**)	Offset, based on the foot of the trapezium
	-(I_{Nom} - **Amplitude**)...+(I_{Nom} - **Amplitude**)	
Time t1	0.1ms...36000000ms	Time for the positive slope of the trapezoidal wave signal.
Time t2	0.1ms...36000000ms	Time for the top value of the trapezoidal wave signal.
Time t3	0.1ms...36000000ms	Time for the negative slope of the trapezoidal wave signal.
Time t4	0.1ms...36000000ms	Time for the base value (=offset) of the trapezoidal wave signal

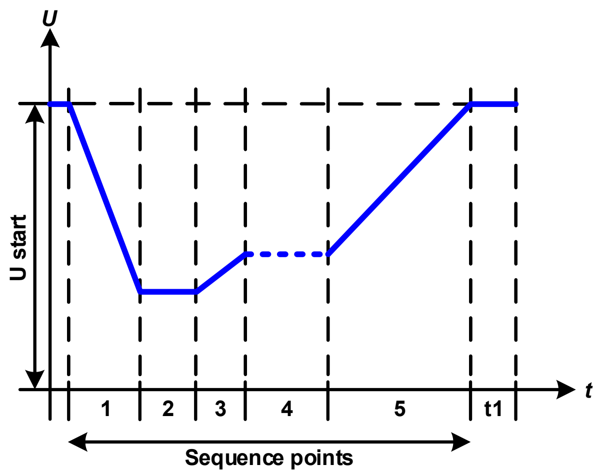
Schematic diagram:	Application and result:
	Same as with other functions the generated signal can be applied to the set value of voltage (U mode) or to the current (I mode). The slopes of the trapezium can be varied by adjusting the times for rise and fall separately. The periodic duration and repetition frequency are the result of the four adjustable time values. With suitable settings the trapezium can be deformed to two triangular or two rectangular pulses. It therefore has universal use.

3.8 DIN 40839 function

This function is based on the curve defined in DIN 40839 / EN ISO 7637 (test impulse 4), and is only applicable to voltage. It shall replicate the progress of automobile battery voltage during engine starting. The curve is divided into 5 parts (see the diagram below) which each have the same parameters. The standard values from the DIN are set already as default values for the five sequences.

Typically, this function is used in source mode, but can also be run in sink mode if the external voltage on the DC terminal is higher than the highest point (offset + amplitude) of the wave and the external source can't deliver more current than adjusted for sink mode (I sink). If not, the device could regulate the voltage values resulting from the curve. The global current set values are used to explicitly define in what operation mode the function shall run. The following parameters can be configured for the single sequence points or the entire function:

Parameter	Range	Seq	Description
Start	0V...U_{Nom}	1-5	Start voltage of the ramp in part 1-5 (sequence point)
Uend	0V...U_{Nom}	1-5	End voltage of the ramp in part 1-5 (sequence point)
Time	0.1ms...36000000ms	1-5	Time of the ramp
Cycles	0 / 1...999	-	Number of times to run the entire curve (0 = infinite)
Time t1	0.1ms...36000000ms	-	Time after cycle before repetition (cycle <> 1)
U(Start/End)	0V...U_{Nom}	-	Voltage setting before and after the function run
I/P (PS)	0A...I_{Nom} / 0W...P_{Nom}	-	Set values of current and power for source mode. If either I=0 or P=0, the device would only work in sink mode
I/P (EL)	0A...I_{Nom} / 0W...P_{Nom}	-	Set values of current and power for sink mode. If either I=0 or P=0, the device would only work in source mode

Schematic diagram:	Application and result:
	If the function is set up to run in source mode, the built-in load function acts as a sink and ensures the quick output voltage drop as required for some parts of the curve, allowing the output voltage progress to follow the DIN curve. The curve conforms to test impulse 4 of the DIN. With suitable settings, other test impulses can be simulated. If the curve part in sequence point 4 should contain a sine wave instead, then these 5 sequences would have to be set up for the arbitrary generator. The global start (and end) voltage is adjustable as parameter **U(Start/end)** in the menu page "U/I/P Limits". It doesn't modify the voltage settings in the single sequence points, but it should match the start voltage setting (U start) of sequence point 1.

3.9 Arbitrary function

The arbitrary (freely definable) function or function generator offers the user a wider scope of options. There are 99 curve segments (here: sequence points) available for use on either current (I) or voltage (U), all of which have the same set of parameters but can be differently configured, so that a complex function curve can be "constructed". An arbitrary number out of the 99 sequence points can run in a sequence point block and this block can then be repeated up to 999 times or infinitely. Since the function must be assigned to either current or voltage, mix assignments of sequence point to both is not possible.

The arbitrary curve can overlay a linear progression (DC) with a sine curve (AC) whose amplitude and frequency is shaped between start and end. When both, start frequency and end frequency, are 0 Hz the AC overlay has no impact and only the DC part is effective. Each sequence point is allocated a sequence point time in which the AC/DC curve will be generated from start to end.

The following parameters can be configured for each sequence point in the arbitrary function:

Parameter	Range	Description
AC start **AC end**	-50%...+50% I_{Nom} or 0%...50% U_{Nom}	Start and end amplitude of the sinusoidal AC part
DC start	±(**AC start**...(rated value - **AC start**))	Start level (offset) of the DC part
DC end	±(**AC end**...(rated value - **AC end**))	End level (offset) of the DC part
Start frequency	0Hz...10000Hz	Start frequency of the sinusoidal AC part
End frequency	0Hz...10000Hz	End frequency of the sinusoidal AC part
Angle	0°...359°	Start angle of the sinusoidal AC part
Time	0.1ms...36000000ms	Time setting for the selected sequence point

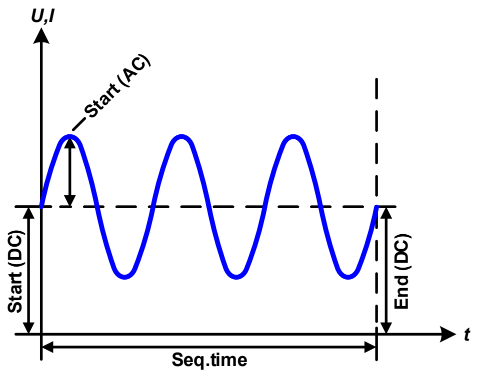
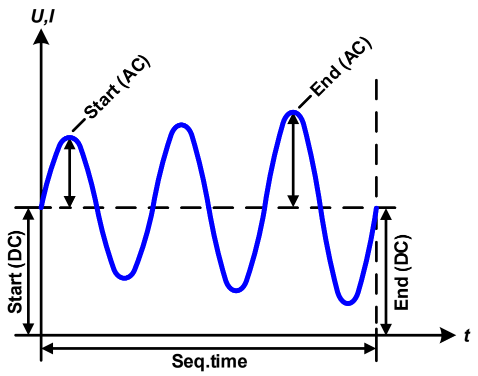
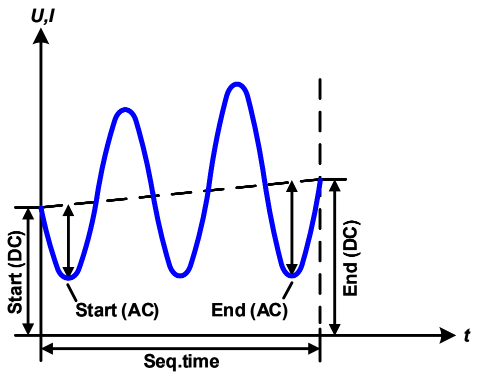
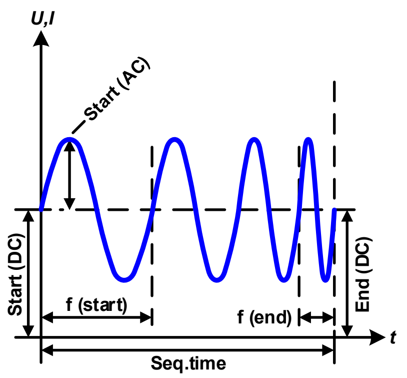
!	*The sequence point time ("Time") and the start and end frequency are related. The minimum value for Δf/s is 9.3. Thus, for example, a setting of start frequency = 1 Hz, end frequency = 11 Hz and time = 5 s would not be accepted as Δf/s is only 2. A time of 1 s would be accepted or, if the time remains at 5 s, then an end frequency = 51 Hz must be set.*

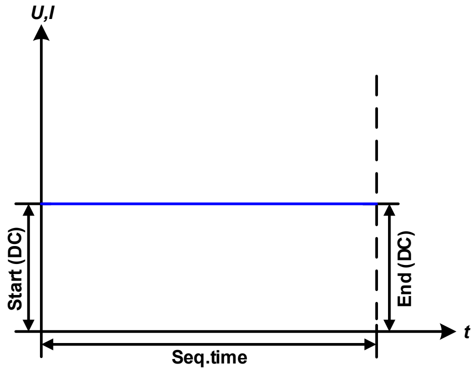
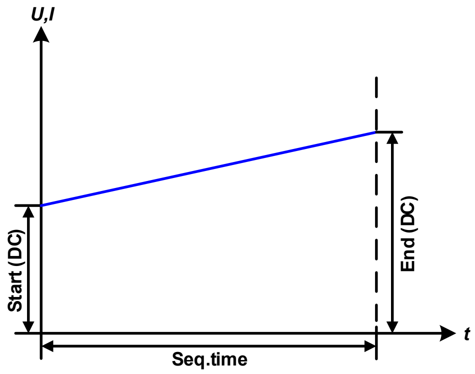
!	*The amplitude change between start and end is related to the sequence time. A minimal change over an extended time is not possible and in such a case the device will report an inapplicable setting.*

After the settings for the selected sequence point have been defined, further points can be configured. Further down there are some global settings for the arbitrary function:

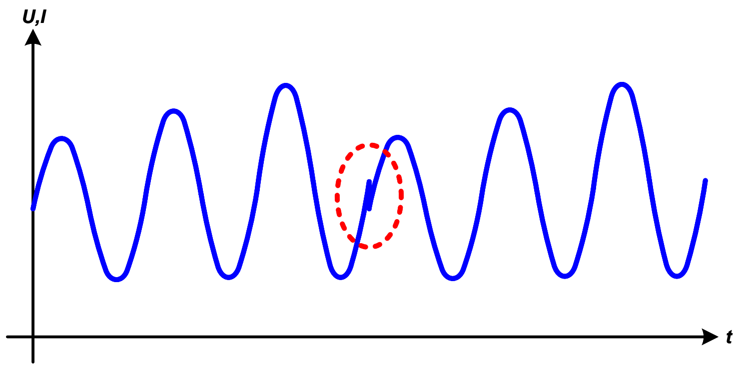
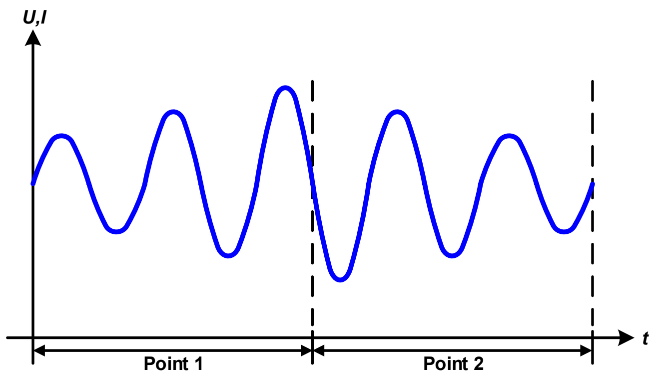
Parameter	Range	Description
Cycles	0 / 1...999	Number of cycles to run the sequence point block (0 = infinite)
Start sequence	1...**End sequence**	First sequence point in the block
End sequence	**Start sequence**...99	Last sequence point in the block

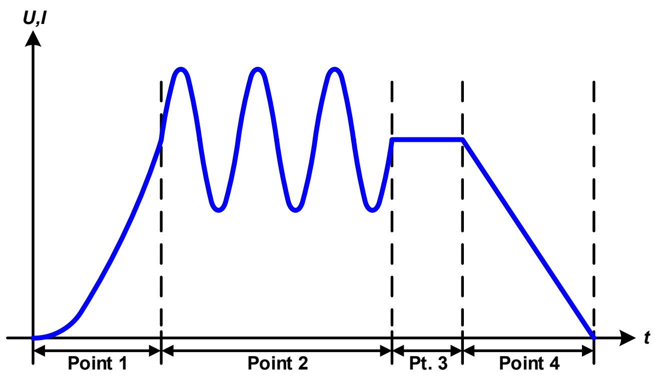
After continuing with  there are global set values to define as the last part of the function generator setup.

Schematic diagram:	Applications and results:
	**Example 1:** Focusing 1 cycle of 1 sequence point: DC values for the start and end are the same, also the AC amplitude. With a frequency >0 Hz a sine wave progression of the set value is generated with a defined amplitude, frequency and Y axis offset (DC values for the start and end). The number of sine waves per cycle depends on the sequence point time and the frequency. If the time was 1 s and the frequency 1 Hz, there would be exactly one sine wave. If the time was 0.5 s at the same frequency, there would only be a half sine wave.
	**Example 2:** Focusing 1 cycle of 1 sequence point: The DC values at the start and end are the same but those of the amplitude aren't. The end value is higher than the start value so the amplitude increases with each new half sine wave continuously over the sequence point time. This, of course, only if time and frequency allow for multiple waves to be created. For instance, with f=1 Hz and time = 3 s, three full waves would be generated, if the angle is 0°, and reciprocally the same for f=3 s and time=1 s.
	**Example 3:** Focusing 1 cycle of 1 sequence point: The DC values at the start and end are not equal, as well as the AC start and end values. In both cases the end value is higher than the start value so that offset increases over time, but also the amplitude with each new half sine wave. Additionally, the first sine wave starts with a negative half wave because the angle has been set to 180°. The start angle can be shifted at will in steps of 1° between 0° and 359°.
	**Example 4:** Focusing 1 cycle of 1 sequence point: Similar to example 1 but with a different end frequency. Here it's shown as higher than the start frequency. This impacts the period of the sine waves such that each new wave will be shorter over the total span of the sequence time.

Schematic diagram:	Applications and results:
	**Example 5:** Focusing 1 cycle of 1 sequence point: Similar to example 1 but with a start and end frequency of 0 Hz. Without a frequency, no sine wave part (AC) will be generated and only the DC settings will be effective. A ramp with a horizontal progression would result.
	**Example 6:** Focusing 1 cycle of 1 sequence point: Similar to example 1 but with a start and end frequency of 0 Hz. Without a frequency no sine wave part (AC) will be generated and only the DC settings will be effective. Here the DC start and end values are unequal and a steadily increasing ramp would result.

By linking together a number of differently configured sequence points, complex progressions can be created. Smart configuration of the arbitrary generator can be used to match triangular, sine, rectangular or trapezoidal wave functions and thus, e.g. a sequence of rectangular waves with differing amplitudes or duty cycles could be produced.

Schematic diagram:	Applications and results:
	**Example 7** Focusing 2 cycles of 1 sequence point: One sequence point, configured as in example 3, is run. Since the settings define that the end offset (DC) is higher than the start, the second run will revert to the same start level as the first, regardless of the signal level at the end of the first run. This can produce a discontinuity in the total progression (marked in red) which may only be compensated with a careful choice of settings.
	**Example 8** Focusing 1 cycle of 2 sequence points: Two sequence points run consecutively. The first one generates a sine wave with increasing amplitude, the second one with a decreasing amplitude. Together they produce a progression as shown on the left. In order to ensure that the wave peak in the middle occurs only once, the first sequence point must end with a positive half wave and the second one start with a negative half wave as shown in the diagram.

Schematic diagram:	Applications and results:
	**Example 9** Focusing 1 cycle of 4 sequence points: Point 1: 1/4th sine wave (angle = 270°) Point 2: Three sine waves (ratio of frequency to time is 1:3) Point 3: Horizontal ramp (f = 0) Point 4: Falling ramp (f = 0)

3.9.1 Loading and saving the arbitrary function

The 99 sequence points of the arbitrary function, which can be manually configured with the control panel of the device and which are applicable either to voltage (U) or current (I), can be saved to or loaded from a common USB stick via the front side USB port. Generally, all 99 points are saved or loaded at once using a text file of type CSV which represents a table of values.

In order to load a sequence table for the arbitrary generator, the following requirements have to be met:

- The table must contain exactly 99 rows with 8 subsequent values (8 columns) and must not have gaps
- The column separator (semicolon, comma) must be as selected by menu parameter **USB logging -> Log file separator format**; it also defines the decimal separator (dot, comma)
- The files must be stored inside a folder called HMI_FILES which has to be in the root of the USB stick
- The file name must always start with WAVE_U or WAVE_I (not case-sensitive)
- All values in every row and column have to be within the specified range (see below)
- The columns in the table have to be in a defined order which must not be changed

Following value ranges are given for use in the table, related to the manual configuration of the arbitrary generator (column headers like in Excel):

Column	Connected to HMI parameter	Range
A	AC start	See the table in *«3.9 Arbitrary function»*
B	AC end	See the table in *«3.9 Arbitrary function»*
C	Start frequency	0...10000 Hz
D	End frequency	0...10000 Hz
E	Angle	0...359°
F	DC start	See the table in *«3.9 Arbitrary function»*
G	DC end	See the table in *«3.9 Arbitrary function»*
H	Time	100...36.000.000.000 µs (36 billion)

For details about the parameter and the arbitrary function refer to *«3.9 Arbitrary function»*.

Example CSV:

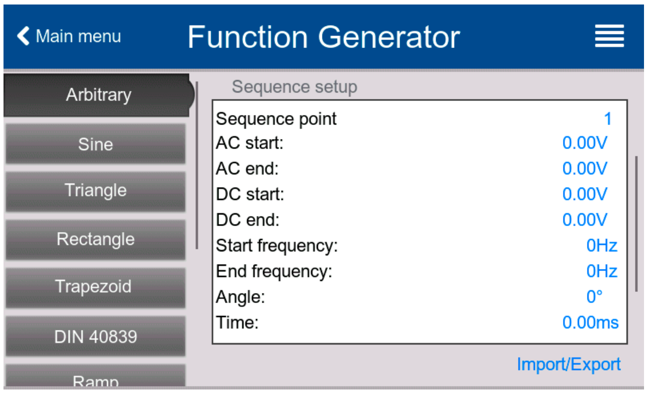
	A	B	C	D	E	F	G	H
1	20,00	30,00	5	5	90	50,00	50,00	50000000
2	30,00	20,00	5	5	90	50,00	50,00	30000000
3	0,00	0,00	0	0	0	0,00	0,00	1000
4	0,00	0,00	0	0	0	0,00	0,00	1000
5	0,00	0,00	0	0	0	0,00	0,00	1000
6	0,00	0,00	0	0	0	0,00	0,00	1000

The example shows that only the first two sequence points are configured, while all others are set to default values. The table could be loaded as WAVE_U or WAVE_I when using, for example, the model PSB 10080-1000 4U, because the values would fit both, voltage and current. The file naming, however, is unique. A filter prevents you from loading a WAVE_I file after you have selected **Arbitrary** --> **U** in the function generator menu. The file would not be listed at all.

► How to load a sequence point table from a USB stick

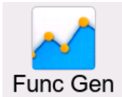
1. Do not plug the USB stick yet or remove it.
2. While the DC terminal is switched off, tap on 

to access the function selection menu. There tap on group **Arbitrary** which will show the settings as shown in the screenshot to the right.
3. Swipe up to go down to the **Sequence setup** part and tap on **Import/Export**, then on **Load** and follow the instructions. If the file open dialog can at least list one compatible file, it will be listed for selection. Select your desired table.



4. To finally load the file, tap on . The selected file is then checked for validity and loaded. In case of format errors, a message will be shown on the screen. The file would have to be checked and tried again.

► How to save a sequence point table to a USB stick

1. Do not plug the USB stick yet or remove it.
2. While the DC terminal is switched off, tap on 

to access the function selection menu. There tap on group **Arbitrary**.
3. Swipe up to go down to the **Sequence setup** part and tap on **Import/Export**, then on **Save** and follow the instructions. In the file open dialog you can either select an existing file, if at least one compatible file is listed, or you can create a new one by not selecting any file.
4. Save the file, new or overwriting, with .

3.10 Ramp function

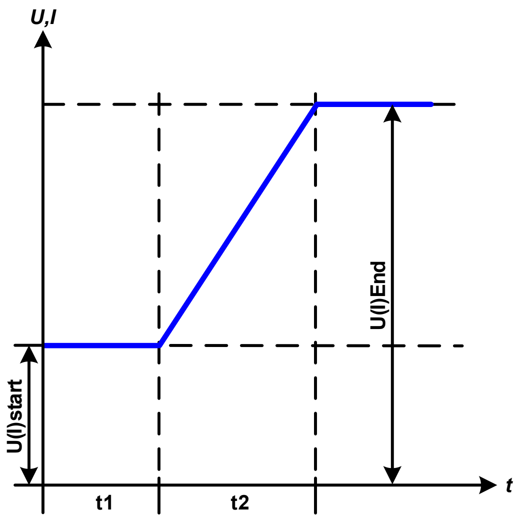
Restrictions which apply particularly to this function:

- There is no preselection to which of both, source mode and sink mode, the function is applied; the settings decide whether it’s “source mode only”, “sink mode only” or a mixture of both
- When applying the function to the voltage, the device can only switch to and work in sink mode if the external voltage on the DC terminal is higher than the highest point (offset + amplitude) of the wave and the current setting “I (EL)” is not 0

The following parameters can be configured for a ramp function:

Parameter	Range	Description
Start End	0V...U_{Nom} or -I_{Nom}...+I_{Nom}	Start/end point of the ramp. Both values can be equal or different, which then results in either a rising, falling or horizontal ramp
Time t1	0.1ms...36000000ms	Time before ramp-up or ramp-down of the signal.
Time t2	0.1ms...36000000ms	Ramp-up or ramp-down time

!	*10 h after reaching the ramp end, the function will stop automatically (i.e. I = 0 A, in case the ramp was assigned to the current), unless it has been stopped manually before.*

Schematic diagram:	Application and result:
	This function generates a rising, falling or horizontally running ramp between the start and end values over time t2. Time t1 creates a delay before the ramp starts. The function runs once and stops at the end value. To have a repeating ramp, the Trapezoid function would have to be used instead (see section *3.7*). Important to consider are the static values of U or I which define the start level before the ramp generation. It's recommended that the corresponding static value is set equal to value **Start**, unless the load at the DC terminal (source mode) shall not be provided with a voltage before the actual start of the ramp (time t1) or the external source shall not yet be loaded with a current in sink mode. In that case the static value should be set to zero.

3.11 IU table function (XY table)

The IU function offers the user the possibility to set a DC current dependent on the voltage being present on the DC terminal. This works in source (PS) or sink (EL) mode. The function is driven by a table with exactly 4096 values, which are distributed over the range 0...125% U_{Nom} of actual voltage on the DC terminal. However, because of the upper limit of 102% of the rated current, only the first 3342 values in the XY table are effective.

The table can either be uploaded from a USB stick through the front side USB port or via remote control (ModBus protocol or SCPI). The function is defined as:

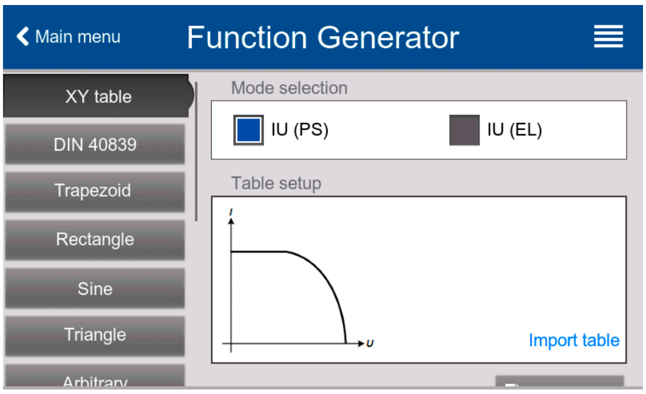
IU function: I = f(U) -> the device works in CC mode (if in source operation, then with a load in CV mode)

!	*Upload of a table from a USB stick must use text files in CSV format (*.csv). Plausibility is checked when loading, i.e. values not too high, number of values correct etc. which may abort loading when errors are found.*

⚠	The 4096 values in the table are only checked for size and count. If all the values were to be graphically plotted into a curve it could include huge step changes in the current. This could lead to complications for the connected load or source if, for example, the internal voltage measurement swings slightly so that the current jumps back and forth between a few entries in the table which, in the worst case, could be bounce between 0 A and the maximum current.

3.11.1 Loading IU tables from USB stick

The so-called IU tables can be loaded from a file via a standard USB stick that is formatted in FAT32. In order to load the file, it has to meet following specifications:



- The file name always begins with IU (not case-sensitive)
- The file must be a text file of type Excel CSV and must only contain one column with exactly 4096 values without gaps
- Values with decimal places must use decimal separator that matches the selection in the general setting **Log file separator format**, which also defines the decimal separator between dot and comma (US default should be dot)
- No value may exceed the rated current of the device model. For example, if you have a 420 A model, none of the 4096 values must be higher than 420 A (the adjustment limits from the device's front panel do not apply here)
- The file(s) has/have to be put inside a folder named HMI_FILES in the root path of the stick

If these specifications are not met, the device won't accept the file and put out an error message in the display. The USB stick may contain multiple IU files with different names and list them for the selection of one.

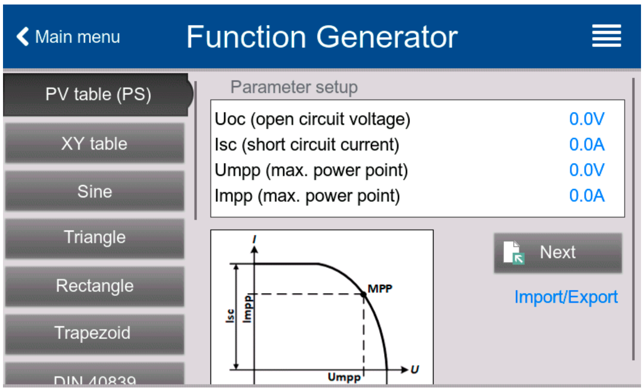
► How to load an IU table from a USB stick

1. While the DC terminal is switched off, open the function selection menu by tapping on Func Gen, then select group **XY table**.
2. In the right-hand part select to run the function in either sink mode with **IU (EL)** or select **IU (PS)** to run the function in source mode.
3. Insert the USB stick, if not already done, then tap on **Import table** and in the file selector coming up select the table you want to load and confirm with ✓. In case the file is not accepted for any of the above listed reasons, correct the file format and content, then try again.
4. Tap Next to proceed to the next screen where you can adjust the global set values.
5. Finally proceed to the main function screen with Next, to start and control the function (also see *«3.3.1 Function selection and control»).*

3.12 Simple PV (photovoltaics) function

3.12.1 Preface

This function runs exclusively in source mode (PS) and uses the integrated XY generator to have the power supply simulate solar panels or cells with certain characteristics by calculating an IU table from four typical parameters.



While the function is running, the user can adjust a 5th parameter called **Irradiance** to simulate different light situations.

The most important characteristics of a solar cell are:

- the short-circuit current (I_{SC}), the maximum current at almost 0 V
- the open circuit voltage (U_{OC}), which almost reaches its maximum value even in low light situations
- the maximum power point (MPP), at which the solar panel can provide the maximum output power, defined by U_{MPP} and I_{MPP}

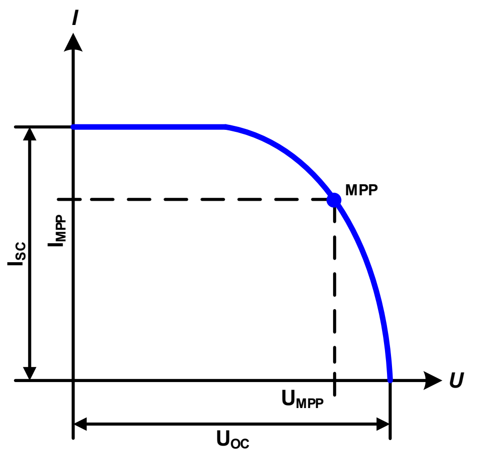
The voltage of the MPP (here: U_{MPP}) lies typically 20% below U_{OC}, the current of the MPP (here: I_{MPP}) lies typically 10% below I_{SC}. In case there are no definite values for the simulated solar cell available, **Impp** and **Umpp** can be set to these typical values. The device limits the I_{MPP} value to I_{SC} as upper limit, the same applies to U_{MPP} and U_{OC}.

3.12.2 Usage

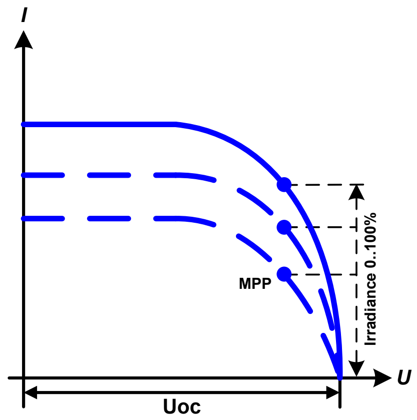
In the PV function, which is based upon the XY generator and an IU table, the MPP (maximum power point) is defined by the two adjustable parameters **Umpp** and **Impp** (also see the diagram below). These parameters are usually stated in data sheets of solar panels and can be entered here.

The following parameters can be set for the PV function:

Parameter	Range	Description
Uoc	**Umpp**...rated device voltage	Open circuit voltage at no load
Isc	**Impp**...rated device current	Short-circuit current at max. load and low voltage
Umpp	0V...**Uoc**	DC terminal voltage of the MPP
Impp	0A...**Isc**	DC terminal current of the MPP

Schematic diagram:	Application and result:
	Adjust all four parameters on the screen to the desired values. Whether the calculated IU and P curves which result from those values make sense or not, can be verified with tools which can visualize the curve data, such as **EA Power Control** (only with unlocked Function Generator app) where you could enter the same values and have the curve visualized with a button click. While the simulation is running, the user can see from the actual values (voltage, current, power) of the DC terminal, where the operating point of the power supply resp. of the simulated solar panel is. The adjustable value **Irradiance** (0%...100% in 1% steps, see the screenshot below) helps to simulate different light situations from darkness (no power output) to the minimal amount of light that is required to have the panel provide full power.

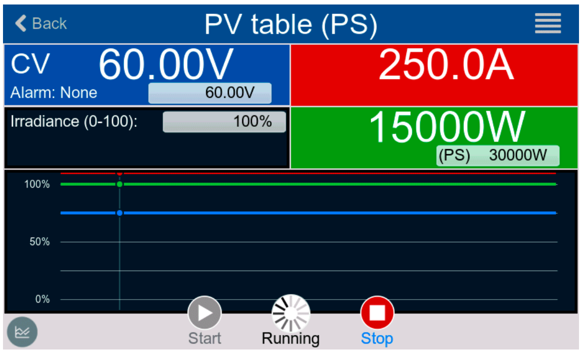
► How to configure the PV table



1. In the function generator menu swipe to find group **PV table (PS)** and tap it.
2. Adjust the four parameters as required for the simulation.
3. Do not forget to adjust the global limits for voltage and power on the next page. The voltage (**U**) setting is automatically set as high as $\mathbf{U_{oc}}$ and should not be lower, but can be higher.
4. Proceed to the main function screen with . Contrary to other functions, the DC terminal is not automatically switched on, because then the function would immediately start. The function is only started when the user switches the DC terminal on.

From the main function generator screen, you can go back to the first screen of PV table function and use a formerly locked **Import/Export** action button to save the calculated table to a USB stick. In order to do so, follow the on-screen instructions. The table can be used to analyze/visualize the values in Excel or similar tools.

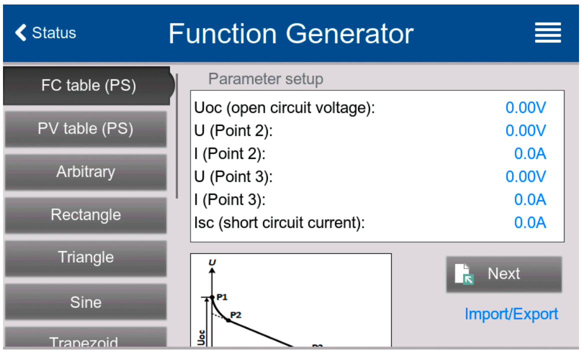
► How to work with the PV table function



1. With an appropriate load connected, for example a solar inverter, start the function.
2. Adjust value **Irradiance** with any rotary knob or per touch input between 100% (default) and 0%, in order to reproduce different light situations for the simulated panel. The actual values on the display indicate the working point and can show whether the simulation has arrived at the MPP or not.
3. Stop the function run anytime with the stop button or by switching off the DC terminal.

3.13 FC table function (fuel cell)

3.13.1 Preface



The FC table function is used to simulate the characteristics of voltage and current of a fuel cell. This is achieved by setting up some parameters which define points on a typical fuel cell curve, which is then calculated as UI table and passed to the internal function generator.

The user has to adjust values for four support points. The device will request them to be entered them step by step, indicating the actual point on screen with small graphics. When finished, these points will be used to calculate the curve.

Generally, the following rules apply when setting up those values:

- $U_{OC} > U_{Point2} > U_{Point3} > U_{Point4}$
- $I_{SC} > I_{Point3} > I_{Point2} > I_{Point1}$
- Values of zero are not accepted

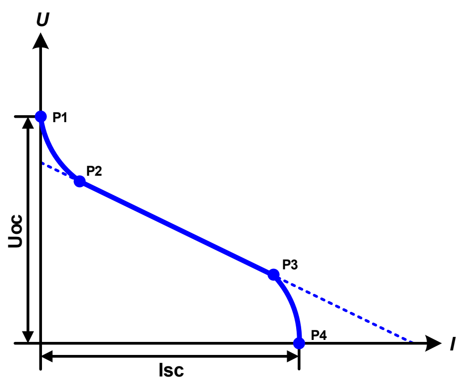
In order to express the rules in a simplified way: the voltage has to decrease from point 1 to point 4, while the current has to increase. In case the rules are not followed, the device will reject the settings with an error and reset them to 0.

3.13.2 Usage

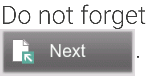
The following parameters can be set for the FC table function:

Parameter	Range	Description
Point 1: Uoc	0V...U_{Nom}	Maximum voltage of the cell (open circuit voltage at no load)
Points 2+3: U	0V...U_{Nom}	Voltage and current define the position of these two points in the XY coordinate system, which represent two supporting points on the curve to be calculated
Points 2+3: I	0A...I_{Nom}	
Point 4: Isc	0A...I_{Nom}	Maximum output current of the fuel cell (short-circuit situation)
U	0V...U_{Nom}	Global voltage limit, should be ≥Uoc
P	0W...P_{Nom}	Global power limit, mustn't be 0 to have the function run as expected

All these parameters all freely adjustable and it may occur that the curve calculation fails. In such a situation, the device would show an error. Then you are required to check the settings, adjust and try again.

Schematic diagram:	Application and result:
	After setting up the four supporting points Point 1 thru Point 4, whereas Point 1 is defined by Uoc and 0 A and Point 4 is defined by Isc and 0 V, the device will calculate the function as IU table and load it to the XY generator. Depending on the load current, which can be between 0 A and Isc, the device should set a variable output voltage between 0 V and Uoc, resulting in a curve similar to the one depicted to the left. The slope between Point 2 and Point 3 is dependent on the values adjusted for Point 2 and Point 3 and can be freely modified as long as Point 3's voltage is lower than the one of Point 2 and Point 3's current is higher than the one of Point 2.

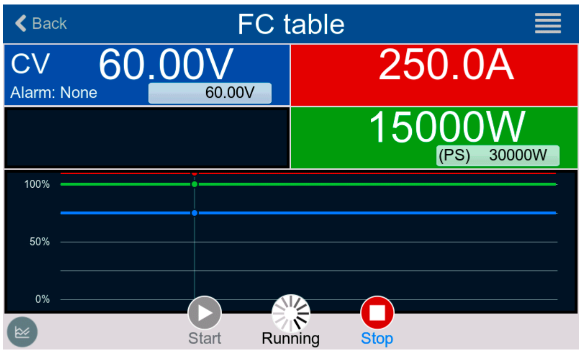
► How to configure the FC table

1. In the function generator menu tap on group **FC table (PS)**.
2. Adjust the parameters of the four supporting points, as required for the simulation.
3. Do not forget to adjust the global limits for voltage and power in the next screen which is reached by tapping on  .
4. After setting everything up, proceed to the main function generator screen with  . After the function has been loaded to the internal XY generator, the simulation is ready to start.

From the main function generator screen, you can go back to the first screen of FC table configuration and use a formerly locked **Import/Export** -> **Save** action button, to save the calculated table to a USB stick. In order to do so, follow the on-screen instructions. The table can be used to analyze the values or to visualize it in Excel or similar tools.

► How to work with the FC table function

1. With an appropriate load connected, for example a DC-DC converter, start the function by switching the DC terminal on.
2. The output voltage will be set depending on the load current, which is defined by the connected load, and will decrease with increasing current. Without any load, the voltage will rise to the adjusted Uoc value.
3. Stop the function run anytime with the stop button or by switching off the DC terminal.



3.14 Extended PV function according to EN 50530

3.14.1 Introduction

This extended PV table function according to norm EN 50530 is used to simulate solar panels in order to test and rate solar inverters. It's also based on the XY generator, same as the simple PV table function from *3.12*, but enables more specific tests and evaluations due to more adjustable parameters, even during runtime. Which parameters are available is explained below. The device can, however, only calculate and run the PV curve. Evaluation of a solar inverter, as described in the norm paper, is only possible with our software **EA Power Control**. It will, amongst other result data, determine the inverter's efficiency.

The impact of the parameters on the PV curve and the simulation is described in the norm paper of EN 50530, which users can refer to in case more detailed description is required. This section only deals about configuration and control of the PV simulation.

3.14.2 Differences to the simple PV function

The extended PV function has a few additional or different characteristics compared to the simple PV function:

- The simulation distinguishes between a single test run and an automatic test run, called day trend, which is based upon a user-defined curve built from up to 100,000 points
- There are two invariable and one variable panel technologies available to choose from
- There are more parameters available to adjust during runtime
- It allows for data recording during runtime and to save the data either to a USB stick or to be read via digital interface

3.14.3 Technologies and technology parameters

When configuring the PV simulation it's necessary to select the solar panel technology to simulate. The technologies **cSI** and **Thin film** are invariable in their parameters, while technology **Manual** is variable in all parameters, but within specific limits. This allows for the variation of the simulation and when copying the fixed parameter values from **cSi** or **Thin film** to **Manual**, it even enables their variation as well.

One advantage of the invariable technologies is that their technology parameters are automatically set to their defined defaults in the configuration procedure.

Overview of the technology parameters used in the PV curve calculation and their defaults:

Abbr.	Name	Manual	cSI	Thin film	Unit
FFu	Fill factor for voltage	**>0...1** (0.8)	0.8	0.72	-
FFi	Fill factor for current	**>0...1** (0.9)	0.9	0.8	-
Cu	Scaling factor for U_{OC} (1	**>0...1** (0.08593)	0.08593	0.08419	-
Cr	Scaling factor for U_{OC} (1	**>0...1** (0.000109)	0.000109	0.0001476	**m²/W**
Cg	Scaling factor for U_{OC} (1	**>0...1** (0.002514)	0.002514	0.001252	**W/m²**
alpha	Temperature coefficient for I_{SC} (2	**>0...1** (0.0004)	0.0004	0.0002	**1/°C**
beta	Temperature coefficient for U_{OC} (1	**-1...<0** (-0.004)	-0.004	-0.002	**1/°C**

(1 Uoc = Open circuit voltage of a solar panel

(2 Isc = Short-circuit current (=max. current) of a solar panel

3.14.4 Simulation mode

Apart from the panel technology there is also a simulation mode to select. Four options:

Mode	Description
U/I	Controllable simulation. Depending on the selected input mode, either the voltage (U_{MPP}, in V) and current (I_{MPP}, in A) in the maximum power point (MPP) or the open circuit voltage (U_{OC}) and short-circuit current (I_{SC}) of the simulated panel will be variable during runtime. The purpose of this mode is to directly shift the MPP into various directions.
E/T	Controllable simulation. During runtime, the irradiation (E from German "Einstrahlung", in W/m²) and surface temperature (T, in °C) of the simulated solar panel are adjustable. This also impacts the curve and the resulting MPP. The purpose of this mode is to analyze the impact of temperature and/or irradiation on the performance of a solar panel.
DAY U/I	Automatic simulation run, processing a day trend curve consisting of up to 100,000 points defined by values for U_{MPP}, I_{MPP} and time.
DAY E/T	Automatic simulation run, processing a day trend curve consisting of up to 100,000 points defined by values for irradiation, temperature and time.

3.14.5 Day trend

The so-called day trend is a special simulation mode for long-term tests. It processes a curve consisting of up to 100,000 user-definable points. For every processed point on that curve, the PV curve is calculated anew.

Every point is defined by 3 values, of which one is the dwell time. When defining long dwell times, the day trend curve can be supported by an interpolation feature which can be optionally activated. It will calculate and set intermediate points between two succeeding curve points. Hence it should be considered to run the day trend with or without interpolation. The day curve points have to be loaded into the device, either from a CSV file on a USB stick or via digital interface. The user selects the number of points according to the requirements of the simulation.

Formats of the CSV files to load from a USB stick when manually configuring the function:

- **For mode DAY E/T** (required file name format: PV_DAY_ET_<arbitrary_text>.csv)

	A	B	C	D
1	1	100	25	300000
2	2	101	25	2000
3	3	102	25	2000
4	4	103	25	2000
5	5	104	25	2000
6	6	105	25	2000
7	7	106	25	2000
8	8	107	25	2000
9	9	108	25	2000

Column A = **Index**

An ascending number between 1 and 100,000 (the first empty index will cause the simulation to stop)

Column B = **Irradiance** (E) in W/m²

Allowed range: 0...1500

Column C = **Temperature** (T) in °C

Allowed range: -40...80

Column D = **Dwell time** in milliseconds (ms)

Allowed range: 500...1.800.000

- **For mode DAY U/I** (required file name format: PV_DAY_UI_<arbitrary_text>.csv)

> ⚠ Attention! The values in columns B and C are real values which must not exceed the ratings of the device or the device will neglect to load the file.

	A	B	C	D
1	1	63.5	120.3	500
2	2	63.6	121.1	500
3	3	63.7	121.9	500
4	4	63.8	122.7	500
5	5	63.9	123.5	500
6	6	64	124.3	500
7	7	64.1	125.1	500
8	8	64.2	125.9	500
9	9	64.3	126.7	500

Column A = **Index**

An ascending number between 1 and 100,000 (the first empty index will cause the simulation to stop)

Column B = **Voltage U_{MPP}** in V

Allowed range: 0...rated output voltage of the device

Column C = **Current I_{MPP}** in A

Allowed range: 0...rated output current of the device

Column D = **Dwell time** in milliseconds (ms)

Allowed range: 500...1.800.000

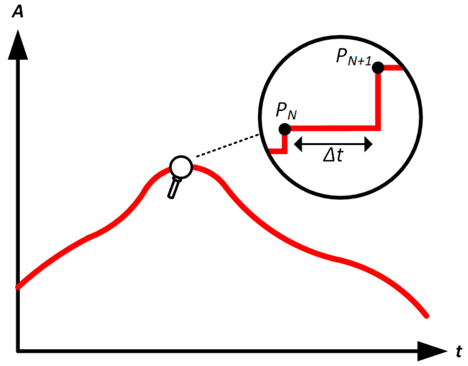
> ❗ *The number format and the column separator in the CSV files is determined by the regional settings of the PC or the software used to create the files. The format must match the selection for the device setting "USB file separator format" in the General Settings menu of the device, else the device would neglect loading the file. For example, an american Excel should by default use the dot as decimal separator and the comma as column separator, which would match the selection "USB file separator format = US".*

3.14.5.1 Interpolation

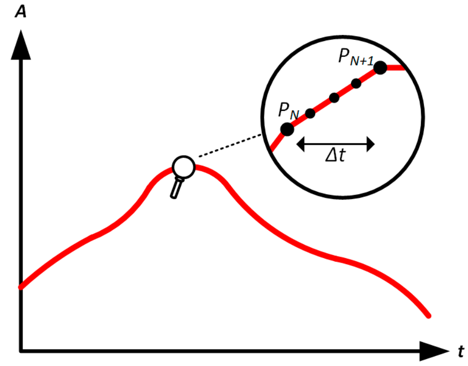
The interpolation feature can calculate and set intermediate steps when running the PV function in day trend mode, i. e. **DAY E/T** or **DAY U/I**. The calculation is always done between to succeeding points on the day trend curve. The dwell time of every curve point is adjustable between 500 and 1,800,000 milliseconds (see above, format of the day trend data file). While there are no extra points calculated when using the minimum time of 500 ms, the following applies to higher dwell time definitions:

- The number of intermediate steps is determined from the dwell time and spread as equally as possible, where any of the steps can have its own dwell time between 500 and 999 ms
- The intermediate steps also respect the slope between the current and the next day trend curve point and therefore every step also includes a corresponding value alteration

Visualization:



Without interpolation - the curve results in steps



With interpolation - the curve remains linear

An example: the dwell time of the 3450th curve point is defined as 3 minutes, which is 180 seconds. There will be 180 / 0.5 -1 = 359 intermediate steps calculated and set until reaching the 3451st point. In mode DAY U/I the MPP voltage changes from 75 V to 80 V and the MPP current changes from 18 A to 19 A. When calculated, this would mean a ΔU/Δt of 27.7 mV/s and a ΔI/Δt of 5.5 mA/s. Depending on the device in use, such small steps in voltage or current may not be realizable. However, the device would try to set the first intermediate step with 75.0138 V and 18.0027 A.

3.14.5.2 Data recording

There is the option to record data during the simulation run, in any mode. The data can be stored to a USB stick once the simulation is finished or read via digital interface, which even allows for reading the data while the simulation is still running.

As long as the simulation is running, the device will record one data set every 100 ms into an internal buffer. This interval is not adjustable. The max. number of data sets, here also called indexes, is 576,000. This results in a maximum recording time of 16 hours. The indexes are internally counted with every new record. When reaching the maximum number, the index will restart from 1, overwriting former data. Every index will contain 6 values.

When configuring the PV simulation, the recording feature is locked at first (button grayed out). Only when stopping the simulation and leaving the control screen back to the configuration, the button becomes accessible. It then allows to store a CSV with a specific number of rows. This number depends on the current index counter. Contrary to remote control where it's possible to address every index of the max. 576,000, saving to a USB stick will always store all indexes between 1 and the counter. Every next simulation run also resets the counter.

CSV file format when saving the recorded data to a USB stick (in the example all values are with unit):

	A	B	C	D	E	F	G
1	Index	U actual	I actual	P actual	Umpp	Impp	Pmpp
2	1	0,29V	0,000A	0,0W	0,00V	0,000A	0,0W
3	2	0,29V	0,000A	0,0W	0,00V	0,000A	0,0W
4	3	0,29V	0,000A	0,0W	0,00V	0,000A	0,0W
5	4	0,29V	0,000A	0,0W	0,00V	0,000A	0,0W
6	5	0,30V	0,000A	0,0W	0,00V	0,000A	0,0W
7	6	0,28V	0,000A	0,0W	0,00V	0,000A	0,0W
8	7	0,28V	0,000A	0,0W	0,00V	0,000A	0,0W
9	8	0,28V	0,000A	0,0W	0,00V	0,000A	0,0W

Index = Ascending number

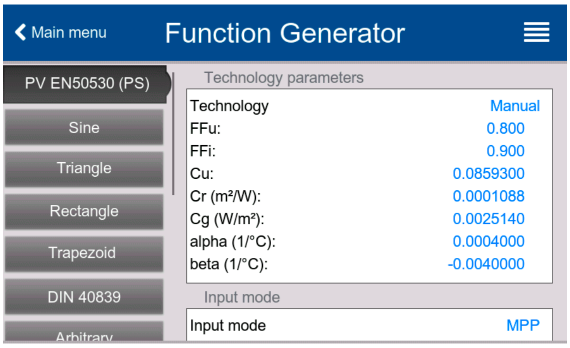
Uactual = Actual voltage on the DC terminal

Iactual = Actual current on the DC terminal

Pactual = Actual power on the DC terminal

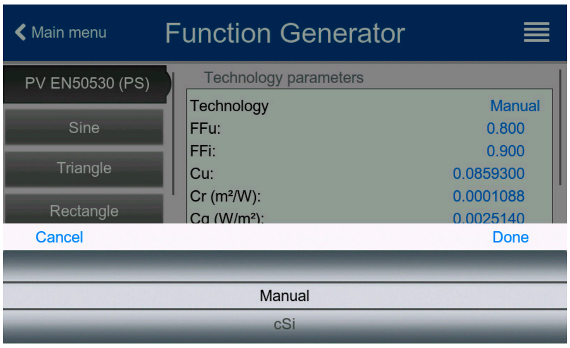
Umpp / Impp / Pmpp = Voltage, current and power in the MPP of the currently calculated PV curve

3.14.6 Step by step configuration



Starting point

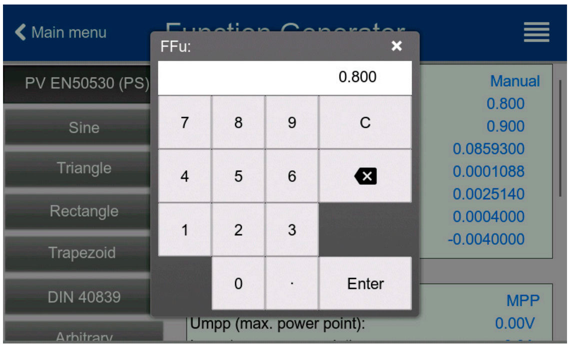
Find the PV functions in the menu **Function Generator**. Select group **PV EN50530 (PS)** here.



Step 1: Technology selection

The extended PV function requires to select the panel technology of the solar panel which is going to be simulated. In case **cSI** or **Thin Film** don't match your requirements or you are not sure about their technology parameters, select **Manual**.

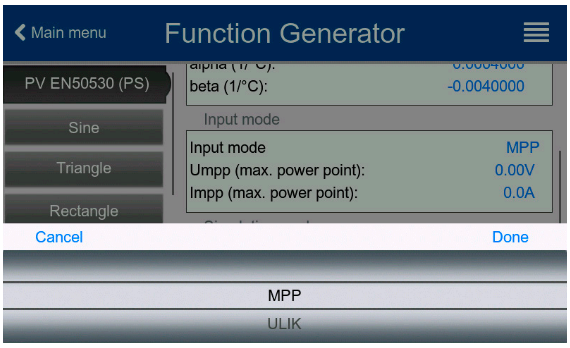
When selecting **Thin film** or **cSI** the configuration continues with **Step 2**.



Step 1-1: Adjust technology parameters

In case technology **Manual** was selected in the previous screen, all displayed technology parameters can be adjusted by tapping on them and entering the desired value. It's recommended to adjust these values very carefully, because wrong settings can result in a PV curve which doesn't work as expected.

When resetting the device, these values are reset to defaults which are the same as with technology **cSI**. Also see the overview in section *3.14.3*. It means they don't necessarily have to be adjusted. If any of the other technologies was selected, this screen would be skipped and these parameters set to the defined values.

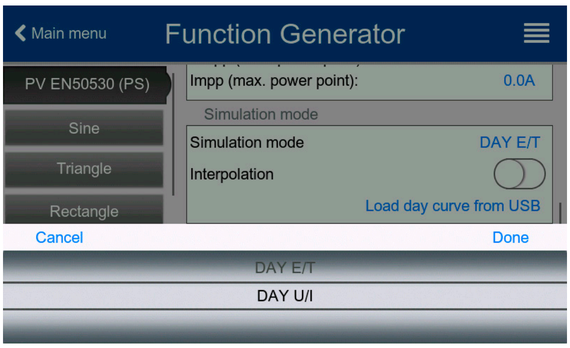


Step 2: Input mode and solar panel base parameters

Selecting the input mode between **MPP** and **ULIK** determines what pair of parameters has to be set in the configuration and also later in the simulation. When setting pair Uoc/Isc, the other pair is calculated with factors and automatically set.

The open circuit voltage (**Uoc**) and the short-circuit current (**Isc**) are upper limits which are usually read from the data sheet of a solar panel and entered here for the simulation. The parameters in the two pairs are connected via the fill factors:

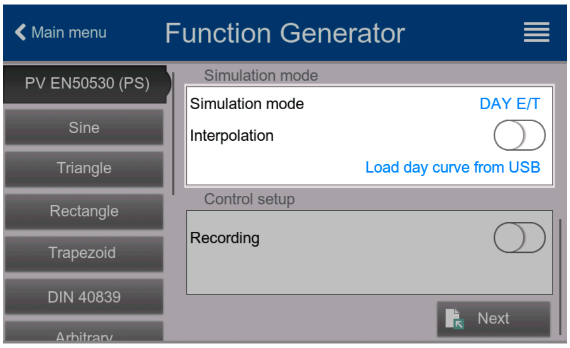
$U_{MPP} = U_{OC} \times FFu$ / $I_{MPP} = I_{SC} \times FFi$



Step 3: Select simulation mode

For a description of the available simulation modes see section *3.14.4*.

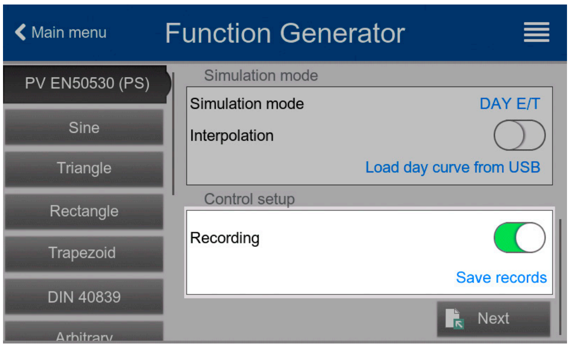
When selecting **E/T** or **U/I** the configuration continues with **Step 4**, otherwise an additional step is required



Step 3-1: Load day trend data

If mode **DAY E/T** or **DAY U/I** is selected, it's necessary to load a curve with day trend data (1-100,000 points) from a USB stick, in form of a CSV file with a specific format (see section *3.14.5*) and name (see section *1.9.6.5* in the installation manual). This is done by tapping on **Load day curve from USB**.

There is furthermore the option to enable (=activate) the interpolation feature. For more about interpolation see section *3.14.5.1*.



Step 4: Rest

One of the last two steps is the option to enable the recording feature, which collects different data than you would get from the regular USB recording. The data is not stored directly to a USB stick, but after stopping the simulation and coming back to the screen, as shown on the left, with button **Save records** now available. Also see section *3.14.5.2*.

Proceed to the next screen with Next. Here you can adjust global set values for voltage and current. These are already set to levels suitable for the simulation.

The configuration will be finished and the settings submitted with button Next. The function generator would then switch to control mode.

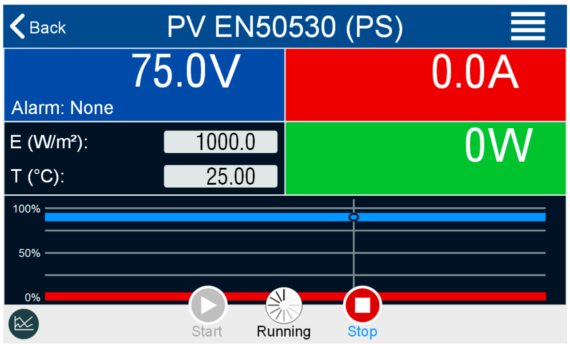
3.14.7 Controlling the simulation

After loading the configured parameters, the FG will switch to control mode. Now the simulation can be started with either the On/Off button or the touch area .

According to the configured simulation mode, the black display area would show the adjustable simulation parameters, which could **only be modified via direct input**, but not by the rotary knobs, because with every step of the knob the curve would be re-calculated.

The screen example on the right shows simulation mode **E/T**.

In case any of the day trend modes has been configured, the display area would be empty. These modes run automatically once started and will stop when the total time of all points' dwell time is reached. The other modes, **E/T** and **U/I**, would only stop by user interaction or due to a device alarm.



3.14.8 Stop criteria

The simulation run could unintentionally stop due to several reasons:

1. A device alarm has occurred, which would switch the DC terminal off (PF, OVP, OCP, OPP)
2. A user event has occurred whose action has been defined as an **Alarm**, which means to switch the DC terminal off

Situation 2 can be avoided by carefully setting up other parameters, unrelated to the function generator. With the simulation stop in both situations, the data recording would also stop.

3.14.9 Test analysis

After the simulation has stopped, by whatever reason, recorded data can be saved to a USB stick or read via any digital interface, of course only if the data recording has been activated in the configuration. Activating the data recording feature during the simulation run isn't possible when manually controlling the FG, but possible in remote control. When saving to a USB stick, it would always save all data recorded until the current index counter. Digital interfaces allow to read any portion of the data, which will also have an impact on the duration of reading a certain number of data sets.

The data can later be used to visualize, analyze and determine characteristics of the simulated solar panel and also of the solar inverter which is usually used as load when running such tests. More details can be found in the standard paper of EN50530.

3.14.9.1 Storing the PV curve

The last PV curve which has been calculated during the simulation run can later be read from the device via any digital interface (partly or completely) or stored on a USB stick. This can serve to verify the adjusted parameters. When running mode DAY E/T or DAY U/I this makes less sense, because then the curve would be re-calculated with every processed index and the read curve would always be the one belonging to the last day trend curve point.

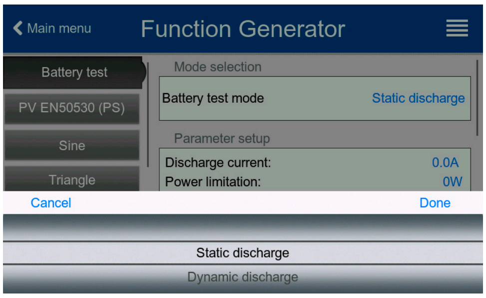
When reading the PV table from the device, you will receive up to 4096 current values. The table data could be visualized in an XY diagram in tools like Excel.

3.15 Battery test function

⚠	The battery test function is only a feature to test batteries. It has no battery management functionality. It means, that there is no monitoring of single battery cells. Dead cells cannot be detected and in case there is at least one dead cell in a battery when being charged or discharged by the device, the battery could be destroyed. External battery management hardware and software might be required.

The purpose of the battery test function is to charge and discharge various battery types in industrial product tests or laboratory applications. Besides separate modes for charging and discharging of a battery, there is also a combination of both available, the so-called dynamic test. This form of test flow is available on the HMI as well as in **EA Power Control** (license based extra which isn't free of charge), but not in digital or analog remote control.

Users programming the device in remote control can achieve a similar flow by configuring the charging test separately from the static or dynamic discharge test and control everything accordingly.

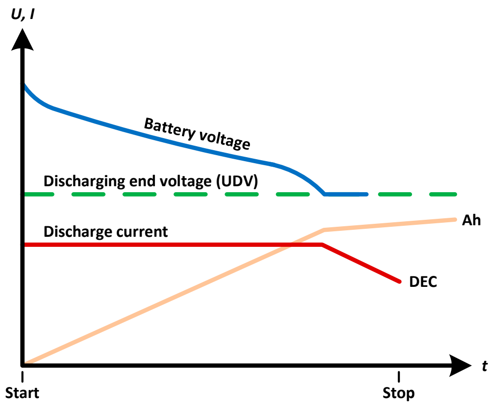


There is a choice of modes: **Static discharge** (constant current), **Dynamic discharge** (pulsed current), **Static charge** (constant current) and **Dynamic test** (flow of charge/discharge).

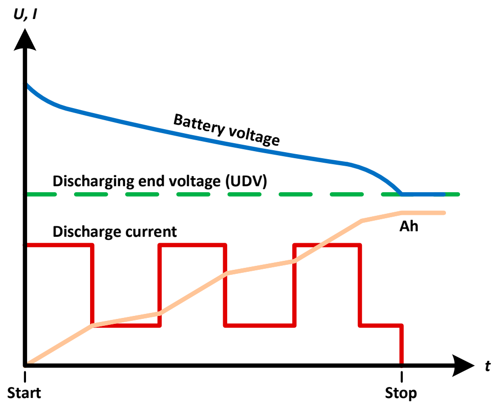
In the **Static discharge** mode, which by default runs in constant current (CC), the device will discharge a battery until it reaches the discharging end voltage (UDV), a point where it switches from to constant voltage mode (CV), discharging the battery further until reaching the discharging end current (DEC), where the test would stop.

For the **Dynamic discharge** mode, there is also a power setting, but it can't be used to run the dynamic battery test function in pulsed power mode or at least the result would not be as expected. It's recommended to always adjust the power value according to the test parameters, so it doesn't interfere with the pulsed current.

Graphical depiction of both discharging modes:



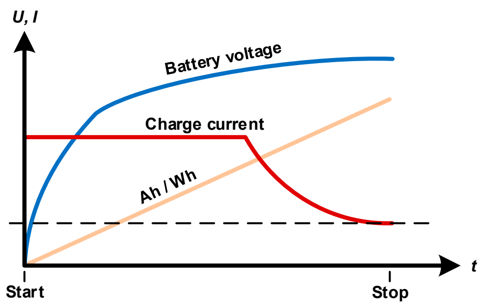
Static discharge



Dynamic discharge

The **Static charge** mode basically follows the charging profile used for lead-acid batteries. The battery is charged with a constant current until it either reaches a specified charging end voltage, a charging end time or when the charging current falls below the specified charging end current threshold.

Graphical depiction of the static charging mode:



The fourth mode is called **Dynamic test** and combines **Static discharge** with **Static charge** in one flow. The same parameters for the single test parts are available, plus some extra for the flow. You can, for example, select what comes first, charge or discharge. There is also an option to cycle the test, i. e. repeat 1 to 999 times or infinitely and you can define a resting period which elapses before the next cycle.

3.15.1 Settings for the static discharge mode

The following parameters can be configured for the static discharge battery test function:

Value	Range	Description
Discharge current	0A...I_{Nom}	Maximum discharge current (in Ampere)
Discharge end voltage	0V...U_{Nom}	Minimum voltage to discharge a battery to (in Volt)

3.15.2 Settings for the dynamic discharge mode

The following parameters can be configured for the dynamic discharge battery test function:

Value	Range	Description
Discharge current 1	0A...I_{Nom}	Upper resp. lower current setting for pulsed operation (the higher value of both is automatically used as upper level)
Discharge current 2	0A...I_{Nom}	
Power limitation	0W...P_{Nom}	Maximum discharge power (in Watt)
Time t1	1s...36000s	t1 = Time for the upper level of the pulsed current (pulse)
Time t2	1s...36000s	t2 = Time for the lower level of the pulsed current (pause)

3.15.3 Settings for the static charge mode

The following parameters can be configured for the static charge battery test function:

Value	Range	Description
Charge voltage	0V...U_{Nom}	Charging voltage (in Volt)
Charge current	0A...I_{Nom}	Maximum charging current (in Ampere)
Charge end current	0A...I_{Nom}	Current threshold (in Ampere) upon which the charging would stop

3.15.4 Settings for the dynamic test mode

The following parameters can be configured for the dynamic test battery test function:

Value	Range	Description
Charge end current	0A...I_{Nom}	Threshold (in Ampere) upon which the charging phase would end
Charge voltage	0V...U_{Nom}	Charging voltage (in Volt)
Charge current	0A...I_{Nom}	Static charging current (in Ampere)
Charge time	1s...36000s	Duration of the charging part (max. 10 h)
Discharge end voltage	0V...U_{Nom}	Threshold (in Volt) upon which the discharging phase would end
Discharge current	0A...I_{Nom}	Static discharging current (in Ampere)
Discharge time	1s...36000s	Duration of the discharging part
Start with	Charge | Discharge	Determines whether the test starts with charging or discharging
Test cycles	0...65535	Number of cycles to run the complete test (0 = infinite cycles)
Rest time	1s...36000s	Time to rest the test before the next phase or cycle

3.15.5 Stop conditions

These parameters are valid for all test modes and define additional stop conditions:

Value	Range	Description
Action: Ah limit	None, Signal, End of test	Enables the optional stop condition
Discharge capacity **Charge capacity** **Test capacity**	0Ah...99999.99Ah	Threshold for the max. capacity to consume from or feed to the battery and after which the test can stop automatically. This is optional, so that also more battery capacity can be consumed or supplied.
Action: Time limit	None, Signal, End of test	Enables the optional stop condition

Value	Range	Description
Discharge time **Charge time** **Test time**	**00:00:00...10:00:00**	Test time after which the test can stop automatically. This stop criteria is optional, it means that single tests can also run longer than 10 h.
Discharge end current	**0A**...I_{Nom}	Only used for: **Static discharge**. This test mode doesn't stop when reaching the discharge end voltage, it would only stop when reaching this current threshold.
Discharge end voltage	**0V**...U_{Nom}	Only used for: **Dynamic discharge**. Minimum voltage (in Volt) to where a battery is discharge and where the test will stop.

3.15.6 Displayed values

During the test run, the display will show various values and statuses:

- Actual battery voltage on the DC terminal
- Discharge end voltage U_{DV} in V (only in discharge mode)
- Charge voltage in V (only in charge mode)
- Actual discharge or charge current
- Actual power
- Total battery capacity (charging & discharging)
- Total battery energy (charging & discharging)
- Elapsed time
- Control mode (CC, CP, CR, CV)

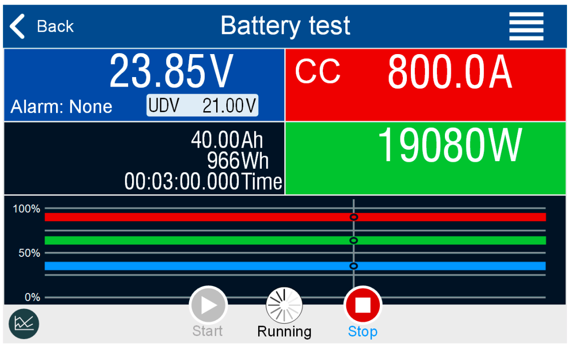


Figure 3 - Example from static discharge

3.15.7 Data recording to USB stick

At the end of the configuration of all test modes there is the option to enable a logging feature:

Value	Range	Description
USB logging	on/off	By setting the check mark, USB logging is enabled and will record data on a properly formatted USB stick, if plugged in to the front USB port. The recorded data differs from the USB log data recorded during "normal" USB logging in all other operation modes of the device.
Logging interval	**100ms - 1s, 5s, 10s**	Writing interval for USB logging

With a USB stick plugged and formatted as required (see section *1.9.6.5* in the installation manual), the device can record data during the test run directly to the stick and in the defined interval. Active USB logging is indicated in the display with a small diskette symbol. After the test has stopped, the recorded data will be available as text file in CSV format.

Log file format example from static discharge mode:

	A	B	C	D	E	F	G
1	Static:Uset	Iset	Pset	Rset	DV	DT	DC
2	0,00V	0,00A	1200W	OFF	0,00V	10:00:00	99999,00Ah
3							
4	Uactual	Iactual	Pactual	Ah	Wh	Time	
5	0,34V	0,00A	0W	0,00Ah	0,00Wh	00:00:00,800	
6	0,28V	0,00A	0W	0,00Ah	0,00Wh	00:00:01,800	
7	0,28V	0,00A	0W	0,00Ah	0,00Wh	00:00:02,800	
8	0,28V	0,00A	0W	0,00Ah	0,00Wh	00:00:03,800	

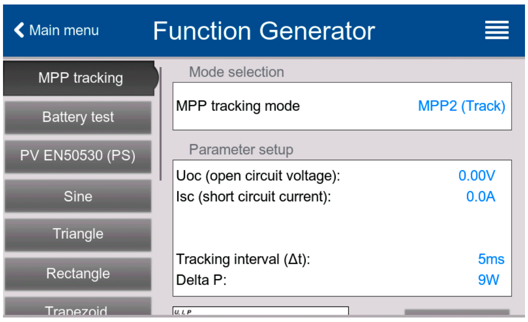
Static = Selected test mode
Iset = Discharging current
Pset = Max. power
Rset = Desired resistance
DV = Discharge end voltage
DT = Discharge end time
DC = Discharge end capacity
U/I/Pactual = Actual values
Ah = Consumed battery capacity
Wh = Consumed energy
Time = Elapsed test time

3.15.8 Possible reasons for a battery test stop

The battery test function run can be stopped due to different reasons:

- Manual stop on the HMI with button **Stop**
- After the max. test time has been reached and action **End of test** was preset
- After the max. battery capacity to consume has been reached and action **End of test** was set for it
- Any device alarm which would also switch off the DC terminal, like OT
- Reaching the threshold U_{DV} (discharge end voltage)
- Reaching the threshold for charging end current

3.16 MPP tracking function

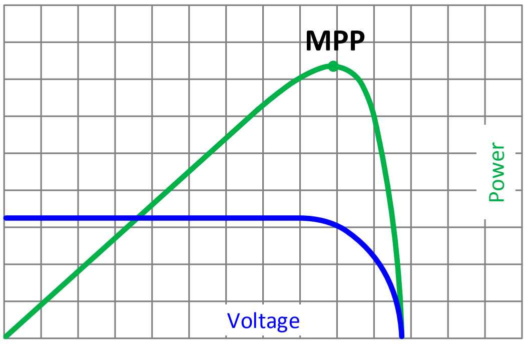


MPP stands for the maximum power point (see the principle view to the right) on the power curve of solar panels. Solar inverters, when connected to such panels, constantly track this MPP once it has been found.

The device imitates this behavior in sink mode. It can be used to test even huge solar panels without having to connect a usually big solar inverter device which also requires to have a load connected to its AC output. Furthermore, all MPP tracking related parameters of the load can be adjusted and it's therefore more flexible than an inverter with its limited DC terminal range.

For evaluation and analysis purposes, the device can also record measured data, i. e. DC terminal values such as actual voltage, current or power, to a USB stick or provide them for reading via any digital interface.

The MPP tracking function offers **four modes**. Unlike with the manual handling of other functions, values for the MPP tracking are only entered by direct input via the touch screen.



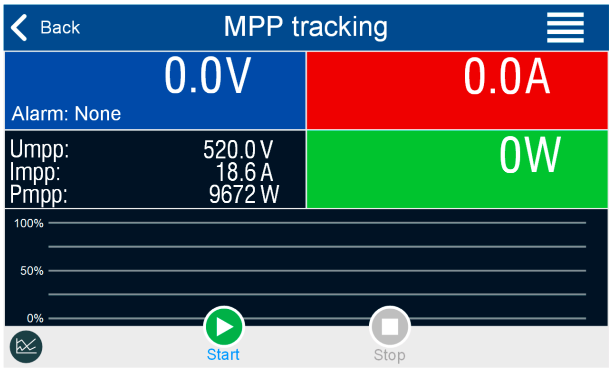
3.16.1 Mode MPP1

This mode is also called "Find MPP". It's the simplest option to have the device find the MPP of a connected solar panel. It's only necessary to set three parameters. Value U_{OC} is required, because it helps to find the MPP quicker than starting at 0 V or maximum voltage.

Actually, it would start at a voltage level slightly above U_{OC}. I_{SC} is used as a upper limit for the current, so the device would not try to draw more current than the panel is specified for. Following parameters can be configured for tracking mode **MPP1**:

Value	Range	Description
U_{OC} (open circuit voltage)	0V...U_{Nom}	Voltage of the unloaded solar panel, taken from the panel specs
I_{SC} (short-circuit current)	0A...I_{Nom}	Short-circuit current, taken from the panel specs
Tracking interval (Δt)	5ms...60000ms	Time between two tracking attempts when finding the MPP

Application and result:



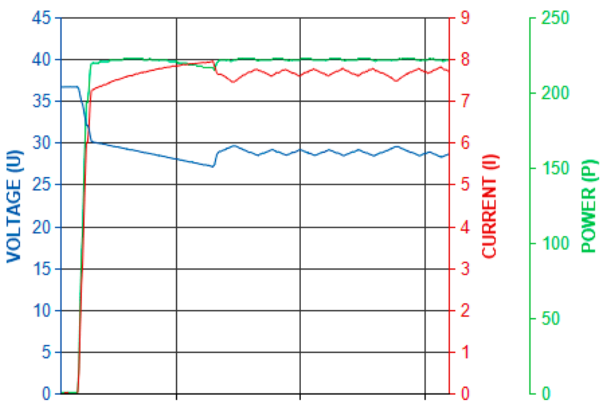
After the three parameters have been set, the function can be started. As soon as the MPP has been found, the function will stop and switch off the DC terminal. The acquired MPP values of voltage (U_{MPP}), current (I_{MPP}) and power (P_{MPP}) would then be shown in the display.

The time of a function run depends on the parameter Δt. Even with the minimum setting of 5 ms, one run usually already takes a few seconds.

3.16.2 Mode MPP2

This mode tracks the MPP, so it's closest to the operation of a real solar inverter. Once the MPP is found, the function won't stop, but will try to track the MPP permanently. Due to the nature of solar panels this can only be done below the level of the MPP. As soon as this point is reached, the voltage starts to sink further and so does the actual power. The additional parameter **Delta P** defines how much the power may fall before the direction is reversed and the voltage starts to rise again until the load reaches the MPP. The result are zigzag shaped curves of both, voltage and current.

Typical curves are shown in the picture to the right. There the **Delta P** was set to a quite small value, so the power curve looks almost linear. With a small **Delta P** the load would always track close to the MPP.



The following parameters can be configured for tracking mode **MPP2**:

Value	Range	Description
U_{OC} (open circuit voltage)	0V...U_{Nom}	Voltage of the unloaded solar panel, taken from the panel specs
I_{SC} (short-circuit current)	0A...I_{Nom}	Short-circuit current, taken from the panel specs
Tracking interval (Δt)	5ms...60000ms	Interval for measuring U and I while finding the MPP
Delta P	0W...P_{Nom}	Tracking/control tolerance below the MPP

3.16.3 Mode MPP3

Also called "fast track", this mode is very similar to mode MPP2, but without the initial step which is used to find the actual MPP, because mode MPP3 would directly jump to the power point defined by user input (U_{MPP}, P_{MPP}). Should the MPP values of the equipment under test be known, this can save a lot of time in repetitive tests. The rest of the function run is the same as with MPP2 mode. During and after the function, the least acquired MPP values of voltage (U_{MPP}), current (I_{MPP}) and power (P_{MPP}) are shown in the display.

The following parameters can be configured for tracking mode **MPP3**:

Value	Range	Description
U_{OC} (open circuit voltage)	0V...U_{Nom}	Voltage of the unloaded solar panel, taken from the panel specs
I_{SC} (short-circuit current)	0A...I_{Nom}	Short-circuit current, taken from the panel specs
U_{MPP} (max. power point)	0V...U_{Nom}	Voltage in the MPP
P_{MPP} (max. power point)	0W...P_{Nom}	Power in the MPP
Tracking interval (Δt)	5ms...60000ms	Interval for measuring U and I while finding the MPP
Delta P	0W...P_{Nom}	Tracking/control tolerance below the MPP

3.16.4 Mode MPP4

This mode is different to the others, because it does not track automatically. It rather offers the choice to define a user curve by setting up to 100 points of voltage values, then track this curve, measure current and power and return the results in up to 100 sets of acquired data. The curve points can only be loaded from a USB stick. Start and end point can be adjusted as well, Δt defines the time between two points and the function run can be repeated up to 65535 times. Once the function stops at the end or due to manual interrupt, the DC terminal is switched off and the measured data is made available. After the function, the acquired set of data with the highest actual power will be shown in the display as voltage (U_{MPP}), current (I_{MPP}) and power (P_{MPP}) of the MPP. Going back one page then allows for data export of the 100 measured results to a USB stick.

The following parameters can be configured for tracking mode **MPP4**:

Value	Range	Description
Start	1...**End**	Start point for the run of x out of 100 subsequent points
End	**Start**...100	End point for the run of x out of 100 subsequent points
Repetitions	0...65535	Number of repetitions for the run from Start to End
Tracking interval (Δt)	5ms...60000ms	Time before the next point

3.16.4.1 Load curve data from USB stick for mode MPP4

Curve point data (only one voltage value per point), in form of a CSV file, is loaded from a USB stick. See section *1.9.6.5* in the installation manual for the naming convention. Contrary to manual adjustment where you can define and use an arbitrary number of points, loading from a USB stick requires the CSV file to always contain the full number of points (100), because it can't define which one is start and end. However, the on-screen setting for the **Start** and **End** points remain valid. It means, if you actually want to use all 100 points from your loaded curve, you must set the parameters accordingly.

File format definition:

- The file must be a text file with appendix *.csv
- The file must contain only one column of voltage values (0... rated voltage)
- The file must contain exactly 100 values in 100 rows, no gaps
- The decimal separator of broken values must follow the setting **Log file separator format** where selection **US** means dot as decimal separator and selection **Standard** means comma

► How to load a curve data file for MPP4

1. While the DC terminal is switched off, enter the function generator by tapping on Func Gen. In the selection swipe up to find group **MPP Tracking** and tap on it.
2. In the area **Mode selection** select **MPP4 (User curve)**. In the lower part under "Parameter" a new tap field **Load MPP4 voltage values** will appear. Tap it.
3. Insert a USB stick, if not already done.
4. The next screen searches the USB stick for compatible files and lists them. Tap the one you want to load and confirm with .

3.16.4.2 Save result data from MPP4 mode to a USB stick

After the MPP4 function has run through, the result data can be saved to a USB stick. The device will always save 100 data sets consisting of the actual values of voltage, current and power belonging to the points it has run through. There is no extra numbering. In case the settings **Start** and **End** were not 1 and 100, the true result data can later be filtered from the file. Points which where not adjusted are automatically set to 0 V, therefore it's very important to carefully adjust the start and end points, because with a voltage setting of 0 V an electronic load would draw its rated current. That's because in this mode, current and power are always set to maximum.

Format of the result data file (for naming convention see section *1.9.6.5* in the installation manual):

	A	B	C
1	1,01V	20,960A	21,0W
2	2,99V	20,970A	63,0W
3	3,99V	20,970A	84,0W
4	5,99V	20,940A	125,0W
5	7,00V	20,920A	146,0W
6	8,00V	20,930A	168,0W
7	9,00V	20,950A	188,0W
8	9,99V	20,960A	210,0W
9	10,99V	20,970A	231,0W

Legend:

- Column A: actual voltage of points 1-100 (= U_{MPP})
- Column B: actual current of points 1-100 (= I_{MPP})
- Column C: actual power of points 1-100 (= P_{MPP})
- Rows 1-100: result data sets of all possible curve points

> **!** *The values in the example table to the left are with physical units. If that's not wanted, they can be turned off in the "General settings" of the device with parameter "USB logging with units (V,A,W)".*

► How to save a curve data file for MPP4

1. After the function has run through, it will stop automatically. Tap on **Back** to go back to the MPP4 configuration screen.
2. Insert a USB stick, if not already done.
3. Below the Next button tap on **Save records**. The next screen searches the stick for compatible files and lists them. Either tap one to select it (overwrite) or don't select any file to create a new file and confirm with .

3.17 Remote control of the function generator

The function generator can be remotely controlled, but configuration and control of the functions with individual commands is different from manual operation. The external documentation "Programming Guide ModBus & SCPI" on the included USB stick explains the approach. In general the following items apply:

- The function generator isn't directly controllable via the analog interface; the only impact to the function run can come from pin REM-SB switching the DC terminal off and on, which will also stop and restart the function
- The function generator is unavailable if R mode (resistance) is activated

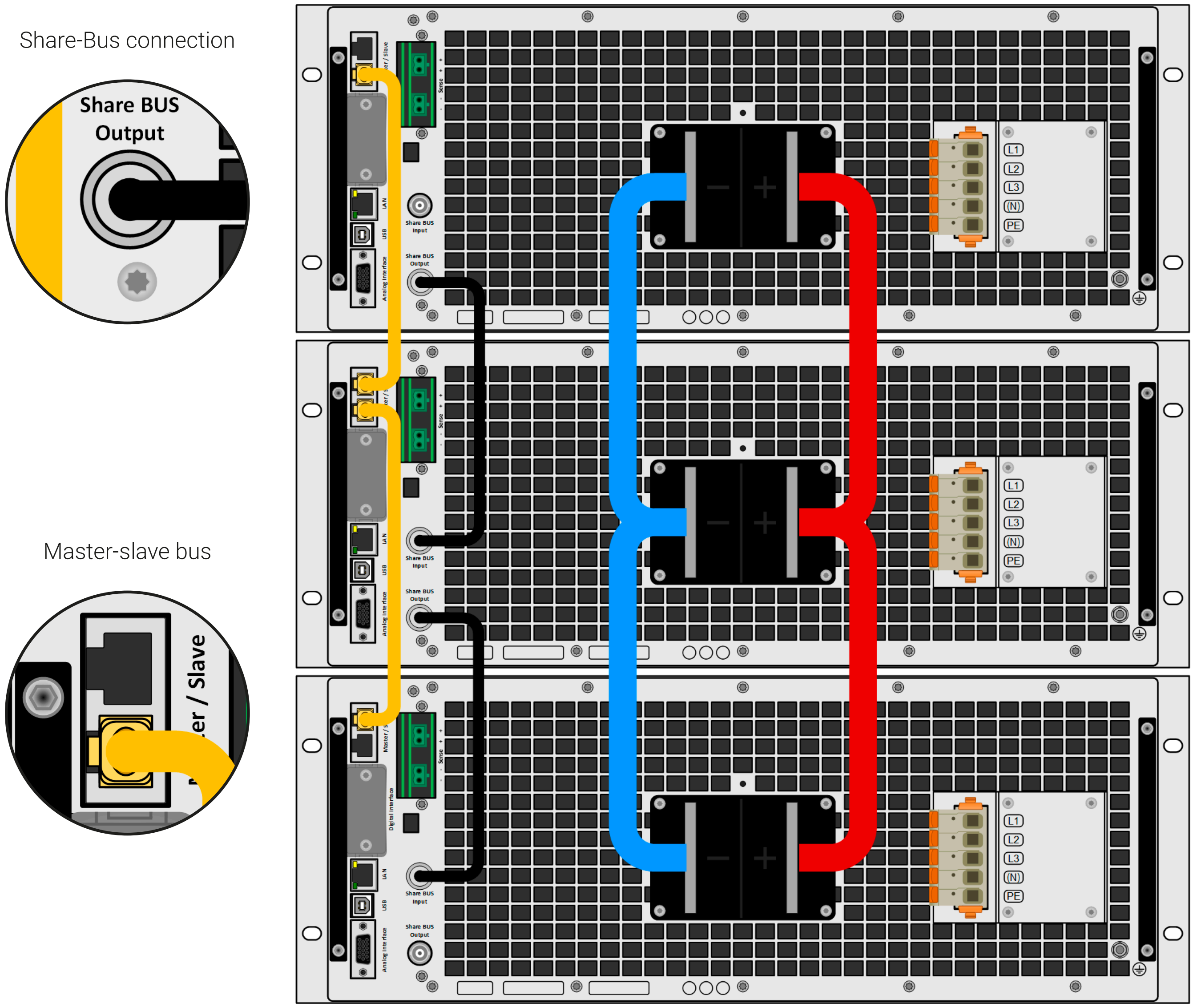
4. Other applications (2)

4.1 Parallel operation in master-slave (MS)

Multiple devices of same kind can be connected in parallel in order to create a system with higher total current and also higher power. For parallel operation in master-slave mode the units are usually connected on their DC terminals, their Share-Bus and their master-slave bus, which is a digital bus that makes the system work as one big unit regarding adjusted values, actual values and status.

The Share-Bus is intended to balance the units dynamically in their voltage on the DC terminal, i.e. in CV mode, especially if the master unit runs a dynamic function. In order for this bus to work correctly, at least the DC minus poles of all units have to be connected, because DC minus is the reference for the Share-Bus.

Principle view (without load or source):



4.1.1 Restrictions

Compared to normal operation of a single device, master-slave operation has some restrictions:

- The MS system reacts partly different in alarm situations (see below in section *4.1.8*)
- Though the Share-Bus makes the system react as dynamic as possible, it's still not as dynamic as single unit operation
- Connection to identical models from other series is supported, but limited to bidirectional 10000 series, such as PSBE 10000 or PUB 10000, which can serve as slave units

4.1.2 Wiring the DC terminals

The DC terminal of every unit in the parallel operation is connected with correct polarity to the next unit, using cables or copper bars with a cross section according to the total system current and with short as possible length, so their inductance is as low as possible.

4.1.3 Wiring the Share-Bus

The Share-Bus is wired from unit to unit with standard BNC cables (coaxial, 50 Ω type) with a length of 0.5 m (1.64 ft) or similar. Both sockets are internally connected and are not specifically input or output. The labeling is only for orientation.

- *A max. of 64 units can be connected via Share-Bus.*
- *When connecting the Share-Bus before a device had been configured as Master or Slave, an SF alarm will occur.*

4.1.4 Wiring and set-up of the master-slave bus

The master-slave connectors are built-in and can be connected via network cables (≥CAT3, patch cable). After this, MS can be configured manually or by remote control. The following applies:

- A maximum of 64 units can be connected via the bus: 1 master and up to 63 slaves.
- Connection only between devices of same kind, i.e. power supply to power supply; connection of different power classes is allowed and supported, e. g. one 15 kW 3U with one 30 kW 4U to achieve a total of 45 kW, but requires to have at least firmware KE/HMI 3.02 installed on all units
- Linking different series is supported, but limited to:
  - PSBE 10000 series models can be used as slave units for PSB 10000 series models being the master unit
- Units at the end of the bus must be terminated (see below for more information)

The master-slave bus must not be wired using crossover cables!

Later operation of the MS system implies:

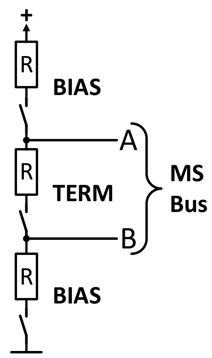
- The master unit displays, or makes available to be read by the remote controller, the sum of the actual values of all the units
- The ranges for setting the values, adjustment limits, protections (OVP etc.) and user events (UVD etc.) of the master are adapted to the total number of units. For example, if 5 units, each with a power of 30 kW, are connected to a 150 kW system, then the master can be set in the range 0...150 kW.
- Slave units are not operable as long as being controlled by the master
- Slave units will show the alarm **MSP** in the display as long as they not have been initialized by the master. The same alarm is signaled after a connection drop to the master unit occurred.
- In case the function generator of the master unit is going to be used, the Share-Bus must be connected as well

► How to connect the master-slave bus

1. Switch off all units and connect the master-slave bus with network cables (CAT3 or better, cables not included). It doesn't matter which of the two master-slave sockets (RJ45, backside) is connected to the next unit.

2. Depending on the desired configuration the units are then also connected at their DC terminals. The two units at the beginning and end of the chain must be terminated, while the master requires a separate setting. See table below.

Termination is done with internal electronic switches which are controlled from within the **Settings** menu of the device in group **Master-slave**. This can be done as part of setting up every unit as master or slave, but should be done before the master is going to be set as **Master**, because doing so immediately triggers a bus initialization. In group **Master-Slave** the termination resistors for BIAS and the bus itself (TERM, see the figure to the right) can be set separately. Settings matrix for the units on the MS bus:



Device position	Termination setting(s)
Master (at end of bus)	BIAS + TERM
Master (central in bus)	BIAS
Slave (at end of bus)	TERM
Slave (central in bus)	-

4.1.5 Mixed systems

As mixed systems following is understood:

- Different power classes, like 5 kW, 15 kW or 30 kW within one master-slave system (requires at least firmware KE 3.02)
- Different series, specifically PSB 10000 series in connection with PUB 10000 series (requires at least firmware KE 3.02)

Both mixed systems are supported, but also their combination. The use of a “PSBE” series device as slave for a “PSB” series master wasn’t possible before, because the PSBE had no resistance mode, contrary to the PSB. Today, this is circumvented by generally enabling resistance control for a PSBE. Vice versa, a PSBE cannot be the master of a PSB.

When connecting devices with different feature sets it makes sense to select the one with the best configuration as master.

Combining different power classes can have an unexpected side effect, such that the resulting total power, as displayed by the master after the initialization, isn’t the expected one, but lower. This depends on what unit and power class has been picked as master. In such a situation the golden rule is: always select the master from the units with the highest power rating.

Example: you want to connect a 30 kW unit and a 3kW unit in order to achieve 33 kW. Generally, the voltage rating must match, but current and power rating can be different. To be precise, the power rating is decisive. When using the 3 kW unit as master, the total system power will only be 28 kW (with a master running firmware KE 3.02), which is even less than the single 30 kW unit. When, however, switching the master to the 30 kW unit, the system will result in 33 kW total power.

4.1.6 Configuring the master-slave operation

Now the master-slave system has to be configured on each unit. It’s recommended to configure all the slave units first and then the master unit.

► Step 1: Configuring all slave units

1. While the DC terminal is switched off, tap  Settings on the main screen to access the **Settings** menu. Swipe up to find group **Master-slave** and tap it.
2. Tapping on the blue button text next to **Mode** will open a selector. By selecting **Slave**, if not already set, the master-slave mode is activated and the device is defined as slave. Additionally, the bus termination can be activated here, if required for the currently configured unit.
3. Leave the Settings menu.

After this, the slave is fully configured for master-slave. Repeat the procedure for all other slave units.

► Step 2: Configuring the master unit

1. While the DC terminal is switched off, tap  Settings on the main screen to access the **Settings** menu. Swipe up to find group **Master-slave** and tap it.
2. Tapping on the blue button text next to **Mode** will open a selector. By selecting **Master**, if not already set, the master-slave mode is activated and the device is defined as master which also automatically enable the BIAS resistor termination, as required for the master.

► Step 3: Initializing the master

When setting a device to Master, it will instantly start to initialize the MS system and the result is displayed in the very same window. In case the initialization is not successful or the number of units or the total power is wrong, it can be repeated in this screen anytime.

Initialization state	Initialized
Number of slaves	1
System voltage	80.00V
System current	2000.0A
System power	60.00kW
System resistance	5.0000Ω
	Initialize system

Tapping **Initialize system** repeats the search for slaves in case the detected number of slaves is less than expected, the system has been reconfigured, not all slave units are already set as **Slave** or the cabling/termination is still not OK. The result window shows the number of slaves plus the total current, power and resistance of the MS system.

In case there are no slaves found at all, the master will still initialize the MS system with only itself.

> **!** *As long as MS mode remains activated, the initialization process of the master-slave system will be repeated each time the master unit is powered. The initialization can also be repeated manually anytime via the Settings menu, in group “Master-Slave”.*

4.1.7 Operating the master-slave system

After successful configuration and initialization of the master and slave units, they will show their status in the status area of their displays. The master would show **MS mode: Master (n Sl)** while the slave(s) would show **MS mode: Slave** plus **Remote: Slave n**, as long they are in remote control by the master.

From now on the slaves can no longer be controlled manually or remotely, neither via the analog nor via any digital interface. They can, if needed, be monitored via these interfaces by reading the actual values and status.

The display on the master unit will reconfigure after initialization and all set values are reset. The master now displays the set and actual values of the total system. Depending on the number of units, the adjustable current and power range will multiply, while the resistance range will decrease, so the following applies:

- The system, represented by the master, can be treated like a standalone unit
- The master shares the set values etc. across the slaves and controls them
- The master is remotely controllable via its analog or one of its digital interfaces
- All settings for the set values U,I, P and R on the master, plus also all related values from supervision, limits etc. should be adapted to the new total values
- All initialized slaves will reset any limits (U_{Min}, I_{Max} etc.), supervision thresholds (OVP, OPP etc.) and event settings (UCD, OVD etc.) to default values, so these don't interfere with the control by the master. As soon as these values are modified on the master, they are transferred 1:1 to the slave(s).
- During MS operation, it might occur that a slave causes an alarm or an event earlier than the master, due to imbalanced current or slightly faster reaction.

> *In order to easily restore all these settings to what was configured before activating MS operation, it's recommended to make use of the user profiles (see «2.3.6 Loading and saving user profiles»)*

- If one or more slaves report a device alarm, it will be signaled on the master and must also be acknowledged there. so that the slave(s) can continue its/their operation. Since an alarm causes the DC terminals to be switched off and can only reinstate the on/off condition automatically after PF or OT alarms, where the reaction to the alarms is configurable, action from an operator or a remote control software may become necessary.
- Loss of connection to any slave will result in the shutdown of the DC terminals of all units as a safety measure and the master will report this situation in the display with a notification showing "Master-slave protection mode". Then the MS system has to be re-initialized, either with or without prior re-establishment of the connection to the disconnected unit(s).
- All units, even the slaves, can be externally shut down on their DC terminals using the pin REM-SB of the analog interface. This can be used as some kind of "emergency off", here usually a contact (maker or breaker) is wired to this pin on all units in parallel.

4.1.8 Alarms and other problem situations

Master-slave operation, due to the connection of multiple units and their interaction, can cause additional problem situations which do not occur when operating individual units. For such occurrences the following regulations have been defined:

- Generally, if the master loses connection to any slave, it will generate an MSP (master-slave protection) alarm, pop up a message on the screen and switch off its DC terminal. The slaves will fall back to single operation mode and also switch off their DC terminal. The MSP alarm can be deleted by initializing the master-slave system again. This can be done either in the MSP alarm requester on the screen or in the MENU of the master or via remote control. Alternatively, the alarm is also cleared by deactivating master-slave on the master unit
- If one or more slave units are cut from AC supply (power switch, blackout, supply undervoltage) and come back later, they're not automatically initialized and included again in the MS system. Then the init has to be repeated.
- If the master unit is cut from AC supply (power switch, blackout) and comes back later, the unit will automatically initialize the MS system again, finding and integrating all active slaves. In this case, MS can be restored automatically.
- If multiple or no units are defined as master the master-slave system can't be initialized

In situations where one or multiple units generate a device alarm like OVP etc., the following applies:

- Any alarm of a slave is indicated on the slave's display and on the master's display
- If multiple alarms happen simultaneously, the master only indicates the most recent one. In this case, the particular alarms can be read from the slave units displays or via digital interface by any software.
- All units in the MS system supervise their own values regarding overvoltage, overcurrent and overpower and in case of alarm they report the alarm to the master. In situations where the current is probably not balanced between the units, it could occur that one unit generates an OCP alarm though the global OCP limit of the MS system was not reached. The same could occur with the OPP alarm.

4.2 SEMI F47

SEMI F47 (the SEMI comes from semiconductor) is a specification that demands a device to continue working without interruption in case of a power failure in form of an AC supply undervoltage (here: sag) of max. -50% of the rated line voltage with a max. duration of 1.7 seconds. From firmware KE 3.02 and HMI 3.02 this has been implemented for all 10000 power supply series, but cannot be obtained by installing an update.

SEMI F47 specifies a AC supply voltage sag in steps of increasing voltage:

Sag of	Duration at 50 Hz	Duration at 60 Hz	Duration in seconds
50%	10 cycles	12 cycles	0.2
30%	25 cycles	30 cycles	0.5
20%	50 cycles	60 cycles	1 s

4.2.1 Restrictions

- The feature will be disabled automatically and also locked if the device boots with low AC supply voltage present, i. e. 208 V (L-L) instead of the default 400 V (L-L), so it could not bridge the 1.7 s duration of the F47 pulse anymore. It means that SEMI F47 isn't available while derating is active.
- It requires a decreased max. power, compared to the rated power of the particular model, thus SEMI F47 is also a sort of derating, but it's not depending on the line voltage but what the AC input circuit (PFC) can cover without running into a power fail. This reduced power rating is activated and deactivated together with SEMI F47

4.2.2 Adjustments

SEMI F47 can either be activated/deactivated manually on the HMI (see section *2.3.1.1*) or a digital interface, unless blocked due to the current device state.

4.2.3 Application

The feature can be activated at any time, unless blocked to the current devices, for example when low voltage derating is already active (see section *2.2.3.1*). With the release of firmwares KE 3.10 and HMI 4.09, the mode **Dynamic** has been added. When just activating SEMI F47 as before, the device will pop up a message after leaving the menu, informing about the altered situation and also instantly reduce the max. available power, as well as adjust the power set value, should the currently adjusted one be higher than the new maximum. When deactivating the feature, it acts vice versa, only the power set value remains unaltered. Due to the fact that the activation of SEMI F47 is stored beyond shutting down the device, it would directly boot into SEMI F47 mode during the next start, also showing that above mentioned requester once after the start (the requester can be deactivated). When using the new mode **Dynamic**, the message won't show. Then the available maximum power isn't reduced permanently, as with mode **Enabled**, but temporarily, for the duration of the sag.

If later a voltage sag occurs, the level of sag or the duration decides whether the device continues its operation without switching the DC terminal off or if it would show a **PF** alarm. Without SEMI F47 being activated, the PF alarm would appear immediately while with activated SEMI F47 it's delayed for at least 2 seconds or will never occur. In this case, the device wouldn't show any reaction to the sag, nor register the occurrence in any form.

5. Service and maintenance (2)

5.1 Firmware updates

⚠	Firmware updates should only be installed when they can eliminate existing bugs in the firmware in the device or contain new features.

The firmware of the control panel (HMI), of the communication unit (KE) and the digital controller (DR), if necessary, is updated via the rear USB port. For this the software EA Power Control is needed, which is included with the device or available as download from our website together with the firmware update, or upon request.

However, it's advisable not to install updates promptly. Every update includes the risk of an inoperable device or system. We recommend to install updates only if...

- an imminent problem with your device can directly be solved, especially if we suggested to install an update during a support case
- a new feature has been added which you definitely want to use. In this case, the full responsibility is transferred to you.

The following additionally applies in connection with firmware updates:

- Simple changes in firmwares can have crucial effects on the application the devices are used in. We recommend to study the list of changes in the firmware history very thoroughly.
- Newly implemented features may require an updated documentation (user manual and/or programming guide, as well as LabVIEW VIs), which is often delivered only later, sometimes significantly later

EA Elektro-Automatik GmbH
Helmholtzstr. 31-37
41747 Viersen
Germany

Phone: +49 (2162) 3785 - 0
ea1974@elektroautomatik.com

www.elektroautomatik.com
www.tek.com